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FORMALISING SCHEDULING THEORIES IN DURATION CALCULUS

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Abstract. Traditionally many proofs in real time scheduling theory were informal and lacked the rigor usually required for good mathematical proofs. Some attempts have been made towards making the proofs more reliable, including using formal logics to specify scheduling algorithms and verify their properties. In particular, Duration Calculus, a real time interval temporal logic, has been used since timing requirements in scheduling can be naturally associated with intervals. This paper aims to improve the work in this area and give a summary. Static and dynamic priority scheduling algorithms are formalised in Duration Calculus and classical theorems for schedulability analysis are proven using the formal proof system of Duration Calculus.

ACM CCS Categories and Subject Descriptors: X.X.X [not known yet]

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1. Introduction

In the classical theory for real time scheduling, scheduling algorithms were invented and then schedulability conditions, i.e., conditions that decide whether or not the set of tasks will meet their timing requirements, were established. For example, in the seminal work by Liu and Layland [Liu and Layland 1973], two scheduling algorithms, i.e., Rate Monotonic Scheduler (RM) and Earliest Deadline First (EDF), were proposed, and schedulability conditions for them were studied. The correctness of the schedulability conditions is not trivial, and therefore needs to be proved as mathematical theorems.

However, in many cases, including those in relatively recent book [Buttazzo 1997], the proofs lack the rigor usually required for good mathematical proofs.

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This is evident in the way in which new concepts were formed, definitions were given and arguments were conducted. In the extreme case, argument was given by diagrams representing execution of tasks, e.g., in the "critical instance" theorem for RM, one can find reasoning like "as shown in Figure" [Liu and Layland 1973,Buttazzo 1997]. Intuitive understanding is surely important, but does not provide the same level of assurance as solid mathematical proofs. Not surprisingly, mistakes sometimes occur and what is indeed true remains uncertain.

Recently, some attempts have been made towards making the work in this area more rigorous. Devillers and Goossens [Devillers and Goossens 2000,Goossens 1999] found several errors and incomplete places in the proofs of Liu and Layland, including the "critical instance" theorem. Goossens [Goossens 1999] studied various scheduling algorithms in details and a considerable amount of effort was put on proofs. Although the work by Devillers and Goossens was a lot more rigorous, the level of formality was still not very high. For example, just as in the earlier work, some definitions were given in natural languages, instead of more precise mathematical terms. Reasoning was in natural language and soundness of some deduction steps is not immediately clear.

In the meantime, completely formal proofs for scheduling theorems have been investigated and we have participated in this effort. In our approach, a mathematical logic, Duration Calculus (DC) [Zhou *et al.* 1991] has been used. DC is a real time extension of the Interval Temporal Logic (ITL) [Moszkowski 1985]. It has been widely applied to specification and verification of various real time systems. The first application of DC to scheduling was due to Zheng and Zhou [Zheng and Zhou 1994], and they proved Liu and Layland's theorem on the EDF. In [Dong *et al.* 1999], Liu and Layland's theorem on the RM scheduler was proven. The same mistake in Liu and Layland's paper reported by Devillers and Goossens [Devillers and Goossens 2000] was independently discovered and corrected. In [Zhan 2000] another proof of the theorem on EDF was given in DC, following the original proof idea of Liu and Layland.

The approach of using DC is as follows.

- Variables are introduced to model the states of the system. For example, Run_i is a Boolean variable of time, and its value is true at time *t* if and only if task τ_i is running at *t*.
- The assumptions, such as the tasks are periodic and they share one processor, is specified by a DC formula *Ass*.
- The concerned scheduling policy, is represented as a DC formula Sch.
- The requirement, in this case, that all task instances should be completed by their deadlines is modelled also as a DC formula *Req*.
 Thus, that a schedulability condition *Cond* is sufficient is formally expressed
 - as the following logical implication in DC: $Ass \wedge Sch \wedge Cond \Rightarrow Req.$
- The proof system of DC is used to prove the theorems.

This paper aims to improve the work in this area and give a summary of it. The remainder of this paper is organized as: Section 2 gives preliminaries of this paper, including a brief review of the basic definitions and results of real-time scheduling

and a short introduction to DC. In Section 3, we formally describe scheduling problems in DC, that is, we specify in DC the assumptions under which the tasks are executed, the underlining algorithms and timing requirements. Section 4 is devoted to fixed priority schedulers. In particular, we prove Liu and Layland's schedulability theorem for RM. This is based on [Dong *et al.* 1999], but we have changed the style of the proof to make it both more readable and more rigorous. Liu and Layland's schedulability theorem for EDF is proved in Section 5. The proof is based on [Zhan 2000], which has not only been improved in style but also considerably in contents. We end this paper with discussions of related work and conclusions. A number of technical lemmas concerning RM are included in the appendix where the mistake in Liu and Layland's paper is reported and corrected.

2. Preliminaries

In this section, we introduce some basic notions and results that will be used later, including a review of the basic concepts of real-time scheduling and an introduction to DC.

2.1 Scheduling real-time tasks on a uniprocessor

In this paper, we study the basic scheduling problem with the following assumptions:

- Tasks are periodic and they start at the same time;
- There is only one processor, and therefore the execution of two tasks is mutually exclusive;
- The deadline of each task is equal to its period;
- The tasks are independent in that requests of a task do not depend on the execution of other tasks;
- Execution time, i.e., the time which is taken by a processor to execute the task without interruption, is constant for a task.

These assumptions allow the complete characterization of a task by two attributes: its request period and its execution time.

A scheduling algorithm is said to be *preemptive* and *priority driven* if whenever there is a request for a task with a higher priority than the task currently being executed, the running task is immediately interrupted and the newly requested task is started. A scheduling algorithm is said to be *static* if priorities are assigned to tasks once and kept unchanged, and a scheduling algorithm is called to be *dynamic* if priorities of tasks may change during the execution.

Rate Monotonic Scheduler statically assigns priorities to tasks according to their request rates, i.e., tasks with higher request rates (shorter periods) have higher priorities. The most well-known dynamic scheduling algorithm is Earliest Deadline First (EDF). In EDF, priorities are assigned to tasks according to the deadlines of their current requests. A task is assigned the highest priority if the deadline of its

current request is the nearest, and is assigned the lowest priority if the deadline of its current request is the furthest.

Given a set of tasks and a scheduling algorithm, the task set is *schedulable* by the algorithm if the requested execution time of each task instance is fulfilled before the deadline. Unless stated otherwise, throughout this paper we shall use $\tau_1, \tau_2, \dots, \tau_m$ to denote *m* tasks, C_1, C_2, \dots, C_m their execution times and T_1, T_2, \dots, T_m their periods. The processor utilisation factor of the tasks is defined as $\sum_{i=1}^{m} C_i/T_i$, and is used in schedulability analysis.

NECESSARY CONDITION: If a set of m tasks is schedulable by any scheduling algorithm, then processor utilisation factor is less than or equal to 1.

Liu and Layland [Liu and Layland 1973] studied sufficient schedulability conditions for RM and EDF:

SUFFICIENT CONDITION FOR RM: A set of m tasks is schedulable by RM, if the processor utilisation factor is less than or equal to $m(2^{\frac{1}{m}} - 1)$.

SUFFICIENT CONDITION FOR EDF: A set of m tasks is schedulable by EDF if the processor utilisation factor is less than or equal to 1.

2.2 Duration calculus

In this subsection, we give a brief review of DC. DC, proposed by Zhou, Hoare and Ravn [Zhou *et al.* 1991], is an extension of real arithmetics and ITL [Moszkowski 1985]. A more comprehensive introduction to DC can be found in [Hansen and Zhou 1997,Zhou and Hansen 2004].

In this paper, we use \mathbb{N} to denote the set of natural numbers and \mathbb{R} the set of reals. DC contains the following sets of symbols:

- A set of global variables $GVar = \{x, y, ...\}$, and the meaning of a global variable is independent of time;
- A set of state variables $SVar = \{P, Q, ...\}$ that are used to model the behavior of systems;
- A set of temporal propositional letters $PLetter = \{X, Y, ...\};$
- A set of global function symbols $FSymb = \{f, g, ...\};$
- A set of global relation symbols $RSymb = \{G, H, ...\}$.

In DC, only functions and relations of real arithmetic are concerned, and therefore a DC model contains

- a total function $\underline{f}_{i}^{n} \in \mathbb{R}^{n} \to \mathbb{R}$ is associated with each *n*-ary function symbols $f_{i}^{n} \in FS$ ymb, and
- a total function $\underline{G}_i^n \in \mathbb{R} \to \{tt, ff\}$ is associated with each *n*-ary relation symbol $G_i^n \in RS$ ymb.
- Here, tt and ff represent Boolean values true and false respectively.

The meaning of global variables is given by a value assignment,

 $\mathcal{V} \in GVar \rightarrow Values$

associating a value with each global variable. Time is represented by the set of non-negative reals, denoted by Time. An interval is a pair of time points, where the beginning time point is no later than the ending point:

$$Intv = \{[b, e] \in \text{Time} \times \text{Time} \mid b \le e\}$$

Interpretations of state variables and propositional letters are defined as follows:

$$I \in SVar \to \text{Time} \to \{0,1\},$$

$$\mathcal{J} \in PLetters \to Intv \to \{0,1\}.$$

State variables are interpreted as functions from Time to Boolean values (denoted by 0 and 1). All state variables are assumed to have *finite variability*, which means that each state variable can only change its value a finite many times over any (finite) interval. A model is a quadruple $(\mathcal{I}, \mathcal{J}, \mathcal{V}, [b, e])$.

A Boolean state expression S is constructed from (Boolean) state variables with Boolean connectives and its duration in a model $(\mathcal{I}, \mathcal{J}, \mathcal{V}, [c, d])$ is defined as

$$(\int S)(I, \mathcal{J}, \mathcal{V}, [b, e]) \widehat{=} \int_{b}^{e} (S)(I, \mathcal{V})(t) dt,$$

where $(S)(\mathcal{I}, \mathcal{V})(t)$ denotes the value of *S* at time *t* under state interpretation \mathcal{I} and valuation \mathcal{V} . The length ℓ of an interval is defined as $\ell = \int 1$ and it is easy to prove that $(\ell)(\mathcal{I}, \mathcal{J}, \mathcal{V}, [c, d]) = d - c$. Primitive formulae of DC are either temporal propositionals letter or those constructed from terms using comparison operators in arithmetics, such as <, = etc. DC formulae are contructed from primitive formulae by Boolean connectives and modality operators. A symbol is called *rigid* if its meaning is independent of time and intervals; otherwise called *flexible*. Global variables, constants, function symbols and relation symbols are rigid, whereas state variables and temporal propositional letters are flexible. A term or formula is called *rigid* if it contains no flexible symbols; otherwise called *flexible*. Boolean state expression *S* holds almost everywhere (i.e., except possibly a finite number of points) over a non-point interval, denoted as [S], is defined as, $[S] = \int S = \ell \wedge \ell > 0$. A point interval is characterised by $\ell = 0$, shortened as []. The modality "chop" of ITL is defined as follows: for any formulae ϕ and ψ ,

$$(I, \mathcal{J}, \mathcal{V}, [b, e]) \models \phi \widehat{\psi} \text{ iff there exists } m \text{ such that } b \le m \le e \text{ and}$$
$$(I, \mathcal{J}, \mathcal{V}, [b, m]) \models \phi \text{ and } (I, \mathcal{J}, \mathcal{V}, [m, e]) \models \psi.$$

The following abbreviations will be used:

As usual, a formula ϕ is valid if for any model $(I, \mathcal{J}, \mathcal{V}, [b, e])$,

 $(I, \mathcal{J}, \mathcal{V}, [b, e]) \models \phi.$

A term θ is said to be *free for x* in ϕ if *x* does not occur freely in ϕ within the scope of $\exists y$ or $\forall y$, where *y* is any variable occurring in θ .

The axioms of DC include those of ITL which are taken from the paper by Dutertre [Dutertre 1995]:

ITL1:	$\ell \ge 0$
ITL2:	$((\phi \psi) \land \neg (\phi \varphi)) \Rightarrow (\phi (\psi \land \neg \varphi))$
	$((\phi \psi) \land \neg (\varphi \psi)) \Rightarrow ((\phi \land \neg \varphi) \psi)$
ITL3:	$((\phi \widehat{\psi} \widehat{\psi} \widehat{\varphi}) \Leftrightarrow (\phi \widehat{\psi} \widehat{\psi}))$
ITL4:	$(\phi \widehat{\psi}) \Rightarrow \phi$, if ϕ is a rigid formula
	$(\phi \hat{\psi}) \Rightarrow \psi$, if ψ is a rigid formula
ITL5:	$(\exists x.\phi \widehat{\psi}) \Rightarrow \exists x.(\phi \widehat{\psi}), \text{ if } x \text{ is not free in } \psi$
	$(\phi \widehat{\exists} x.\psi) \Rightarrow \exists x.(\phi \widehat{\psi}), \text{ if } x \text{ is not free in } \phi$
ITL6:	$((\ell = x)\widehat{\phi}) \implies \neg((\ell = x)\widehat{\neg}\phi)$
	$(\phi\widehat{}(\ell=x)) \implies \neg(\neg\phi\widehat{}(\ell=x))$
ITL7:	$(x \ge 0 \land y \ge 0) \Rightarrow ((\ell = x + y) \Leftrightarrow ((\ell = x)^{\frown}(\ell = y)))$
ITL8:	$\phi \Rightarrow (\phi \widehat{\ }(\ell = 0))$
	$\phi \Rightarrow ((\ell = 0)\hat{\phi})$

and the following axioms about durations:

DCA1:
$$\int 0 = 0$$

DCA2: $\int 1 = \ell$
DCA3: $\int S \ge 0$
DCA4: $\int S_1 + \int S_2 = \int (S_1 \lor S_2) + \int (S_1 \land S_2)$
DCA5: $((\int S = x) \frown (\int S = y)) \Rightarrow (\int S = x + y)$
DCA6: $\int S_1 = \int S_2$, provided $S_1 \Leftrightarrow S_2$ holds in propositional logic

The inference rules of DC include:

MP:	if ϕ and $\phi \Rightarrow \psi$ then ψ (modus ponens)
G:	if ϕ then $\forall x.\phi$ (generalization)
Q:	$\forall x.\phi(x) \Rightarrow \phi(\theta)$ if either θ is free for x in $\phi(x)$ and θ is rigid or θ is free for x in $\phi(x)$ and $\phi(x)$ is chop free.
N:	if ϕ then $\neg(\neg \phi \widehat{\psi})$ if ϕ then $\neg(\psi \widehat{\neg} \phi)$
M:	if $\phi \Rightarrow \psi$ then $(\phi \widehat{\ }\varphi) \Rightarrow (\psi \widehat{\ }\varphi)$

if $\phi \Rightarrow \psi$ then $(\varphi \widehat{\phi}) \Rightarrow (\varphi \widehat{\psi})$

IR1: Let H(X) be a formula possibly containing the propositional letter X, and S_1, \ldots, S_m be m state expressions with $S_1 \lor \ldots \lor S_m = 1$.

If H([]) and $H(X) \Rightarrow H(X \lor (X \cap S_1]) \lor \ldots \lor (X \cap S_m]))$, then H(tt),

where $H(\phi)$ denotes the formula obtained from H(X) by replacing X in H with ϕ .

IR2: Let H(X) be a formula possibly containing the propositional letter X, and S_1, \ldots, S_m be m state expressions with $S_1 \lor \ldots \lor S_m = 1$.

If H([]) and $H(X) \Rightarrow H(X \lor ([S_1]^X) \lor \ldots \lor ([S_m]^X))$, then H(tt).

The above proof system is sound and relative complete in the sense that all valid formulae of ITL are assumed to be provable [Hansen and Zhou 1997, Zhou and Hansen 2004].

Using the proof system, we can easily prove the following theorems which will be used later. Below, variables x and y are assumed to be non-negative:

DC1
$$(tt^{\uparrow}tt) \Leftrightarrow tt$$

DC2-1 $(\phi^{\frown}(\psi \lor \varphi)) \Leftrightarrow ((\phi^{\frown}\psi) \lor (\phi^{\frown}\varphi))$
DC2-2 $((\phi \lor \psi)^{\frown}\varphi) \Leftrightarrow ((\phi^{\frown}\varphi) \lor (\psi^{\frown}\varphi))$
DC3 $(\int S \ge x) \Leftrightarrow ((\int S = x)^{\frown}tt)$
DC4-1 $(\phi^{\frown}(\ell = 0)) \Rightarrow \phi$
DC4-2 $((\ell = 0)^{\frown}\phi) \Rightarrow \phi$
DC5-1 $((\Box\phi) \land (\psi^{\frown}\varphi)) \Rightarrow ((\phi \land \psi)^{\frown}\varphi)$
DC5-2 $((\Box\phi) \land (\psi^{\frown}\varphi)) \Rightarrow ((\phi \land \psi)^{\frown}\varphi)$
DC6 $((\Box_{p}\phi) \land (\psi^{\frown}\varphi)) \Rightarrow ((\phi \land \psi)^{\frown}\varphi)$
DC7-1 $(\Box\phi) \land (\Box_{p}\psi) \Leftrightarrow (\Box_{p}(\phi \land \psi))$
DC7-2 $(\Box_{p}\phi) \land (\Box_{p}\psi) \Leftrightarrow (\Box_{p}(\phi \land \psi))$
DC8-1 $(\Box\phi) \Rightarrow \phi$
DC8-2 $(\Box_{p}\phi) \Rightarrow \phi$
DC9 $((\diamond_{p}\phi) \land (\Box\psi)) \Rightarrow (\diamond_{p}(\phi \land \psi))$
DC10 $\exists x.(\ell = x)$
DC11 $(\lceil S_{1} \rceil \land \lceil S_{2} \rceil) \Leftrightarrow \lceil S_{1} \land S_{2} \rceil$
DC12 $\lceil \neg S \rceil \Rightarrow (\int S = 0)$
DC13 $(\ell = 0) \Rightarrow (\int S = 0$
DC14-1 $\lceil S \rceil \Leftrightarrow (\lceil S \rceil \lnot \lceil S \rceil)$
DC15-1 $((\phi^{\frown}\psi) \land (\lceil S \upharpoonright \lor \rceil)) \Rightarrow ((\phi \land (\lceil S \rceil \lor \lceil)))^{\frown}(\psi \land (\lceil S \rceil \lor \lceil))))$

$$\begin{array}{lll} \mathrm{DC15-2} & ((\phi \widehat{\lor} \psi) \land (\int S < x)) \Rightarrow ((\phi \land (\int S < x))\widehat{\lor} (\psi \land (\int S < x))) \\ \mathrm{DC16-1} & ((\phi_1 \land (\ell = x))\widehat{\lor} \psi_1 \land (\phi_2 \land (\ell = x)))\widehat{\lor} \psi_2) \Rightarrow \\ & ((\phi_1 \land \phi_2 \land (\ell = x))\widehat{\lor} (\psi_1 \land \psi_2)) \\ \mathrm{DC16-2} & (\phi_1\widehat{`} (\psi_1 \land (\ell = x)) \land \phi_2\widehat{`} (\psi_2 \land (\ell = x)))) \Rightarrow \\ & ((\phi_1 \land \phi_2)\widehat{`} (\psi_1 \land \psi_2 \land (\ell = x))) \\ \mathrm{DC17} & ((\int S < x) \land (\ell \ge y)) \Leftrightarrow ((\int S < x)\widehat{`} (\ell = y)) \\ \mathrm{DC18} & ((\int S \le x) \land ((\int S \ge y)\widehat{`} t)) \Rightarrow (x \ge y) \\ \mathrm{DC19} & ((\int S \ge x)\widehat{`} (\int S \ge y)) \Rightarrow (\int S \ge x + y) \\ \mathrm{DC20} & (\int S \ne \ell) \Rightarrow (tt\widehat{`} \lnot S]\widehat{`} (\int S = \ell)) \text{ and } (\int S \ne 0) \Rightarrow \\ & (tt\widehat{`} S]\widehat{`} (\int S = 0)) \\ \mathrm{DC21} & ((\sum_{i=1}^m \int S_i \le \ell)\widehat{`} (\sum_{i=1}^m \int S_i \le \ell)) \Rightarrow (\sum_{i=1}^m \int S_i \le \ell) \\ \mathrm{DC22} & ((\int S \le [\ell/T]C) \land ((\int S = [\ell/T]C)\widehat{`} (\ell = x)))) \Rightarrow \\ & (tt\widehat{`} ((\ell = x) \land (\int S \le [\ell/T]C))) \\ \mathrm{DC23} & ((\int S \le [\ell/T]C) \land ((\int S = [\ell/T]C)\widehat{`} (\ell = x)))) \Rightarrow \\ & (tt\widehat{`} ((\ell = x) \land (\int S \le [\ell/T]C))) \\ \mathrm{DC24} & ((\int S \le [\ell/T]C) \land ((\int S = [\ell/T]C)\widehat{`} (\ell = x))) \Rightarrow \\ & (tt\widehat{`} ((\ell = x) \land (\int S \le [\ell/T]C))) \\ \end{array}$$

DC22, DC23 and DC24 hold due to the following properties of real numbers:

$$\lceil a/c \rceil + \lceil b/c \rceil \ge \lceil (a+b)/c \rceil$$
 and $\lceil a/c \rceil + \lfloor b/c \rfloor \ge \lfloor (a+b)/c \rfloor$,

where $a, b \ge 0$, c > 0, $\lceil a/c \rceil$ and $\lfloor a/c \rfloor$ denote respectively the smallest integer greater than or equal to a/c and the largest integer less than or equal to a/c.

The following rules can be derived:

- DC25 if $(\phi_1 \wedge \dots \wedge \phi_n) \Rightarrow \psi$ is a theorem, where each ϕ_i starts with \Box , then $(\phi_1 \wedge \dots \wedge \phi_n) \Rightarrow (\Box \psi)$ is also a theorem,
- DC26 if $(\phi_1 \land \dots \land \phi_n) \Rightarrow \psi$ is a theorem, where each ϕ_i starts with \Box or \Box_p then $(\phi_1 \land \dots \land \phi_n) \Rightarrow (\Box_p \psi)$ is also a theorem.

As special cases, if ψ is a theorem, then $\Box \psi$ and $\Box_p \psi$ are also theorems.¹

2.3 Proof style

Dijkstra and Scholten introduced calculational proof [Dijkstra and Scholten 1990] as a way of writing practical proofs. In the calculational style, a typical proof of a scheduling theorem in this paper is of the form exemplified in Fig. 1.

In the proof, many of the subformulae, such as Q_1 and P_4 are repeated many times. In a complex proof, the subformulae may be quite long, so the proof will take a lot of space. Moreover, the subformula that is being transformed in one step is mixed with subformulae that are not changed, and therefore the readability

¹ This is not the same as saying $(\psi \Rightarrow \Box \psi)$ and $(\psi \Rightarrow \Box_p \psi)$ are theorems. They are in fact not.

$P_1 \wedge P_2 \wedge P$	$P_3 \wedge P_4$		(1)
$\Rightarrow Q_1 \wedge Q_2 \wedge P$	$P_2 \wedge P_3 \wedge P_4$	{hints for $P_1 \Rightarrow Q_1 \land Q_2$ }	(2)
$\Rightarrow Q_1 \land (\exists x.Q_3)$	$(A_3) \wedge P_3 \wedge P_4$	{hints for $Q_2 \land P_2 \Rightarrow (\exists x.Q_3)$ }	(3)
$\Rightarrow Q_1 \wedge (\exists x.(Q$	$(P_3 \wedge Q_4)) \wedge P_3 \wedge P_4$	{hints for $Q_3 \land P_3 \Rightarrow Q_4$ }	(4)
$\Rightarrow Q_1 \wedge (\exists x.(Q$	$(P_4 \wedge Q_5)) \wedge P_4$	{hints for $Q_3 \land P_3 \Rightarrow Q_5$ }	(5)
$\Rightarrow Q_1 \wedge (\exists x.(Q$	$Q_4 \wedge Q_5 \wedge (R_1 \vee R_2))) \wedge P_4$	$\{R_1 \lor R_2 \text{ is a tautology }\}$	(6)
$\Rightarrow Q_1 \wedge (\exists x.((q$	$Q_4 \wedge R_1) \vee (Q_5 \wedge R_2))) \wedge P_4$	{(6)}	(7)
$\Rightarrow Q_1 \wedge (\exists x.(Q$	$Q_6 \lor (Q_5 \land R_2))) \land P_4$	{hints for $Q_4 \wedge R_1 \wedge P_4 \Rightarrow Q_6$ }	(8)
$\Rightarrow Q_1 \wedge (\exists x.(Q$	$Q_6 \vee Q_6))$	{hints for $Q_5 \wedge R_2 \wedge P_4 \Rightarrow Q_6$ }	(9)
$\Rightarrow Q_1 \land (\exists x.Q_0)$	5)	{(9)}	(10)
$\Rightarrow Q_7$		{hints for $Q_1 \land (\exists x.Q_6) \Rightarrow Q_7$ }	(11)

Fig. 1: A typical proof of a scheduling theorem in the calculational style.

is poor. In fact, during the process of a proof, one would most likely only wish to write down the subformula that is being transformed. In [Back *et al.* 1997], Back, Grundy and von Wright proposed a way to structure the calculational proof in which only the subformula that is being transformed is written. We adopted a similar style in our previous work [Dong *et al.* 1999,Zhan 2000], and in particular, we used labels to refer to subformulae. However, our style did not express the relation between the formulae explicitly. In this paper, we adopt the idea from [Back *et al.* 1997], but continue to use labels to refer to subformulae as compared to repeating the formulae to simplify the presentation. As an example, the previous proof template will be presented in our new style in Fig 2.

3. General Scheduler Assumptions

In this section, we specify the assumptions that hold for schedulers in general, and deduce a number of basic properties from these assumptions.

3.1 State variables

Two state variables Run_i and Std_i are introduced for each task τ_i . The intention is that Run_i has the value 1 at time *t* if and only if τ_i is running on the processor at the time point, and Std_i has the value 1 if and only if τ_i still needs processing time. The accumulated run time of task τ_i on an interval is given by $\int \operatorname{Run}_i$. A task is running at time *t* only if it has a standing request at *t* and this holds for every task and each time point of every interval. We therefore have the following assumption:

$$A_1 \cong \bigwedge_{i=1}^m \Box ([\operatorname{Run}_i] \Longrightarrow [\operatorname{Std}_i]).$$

$P_1 \wedge P_2 \wedge P_3 \wedge P_4$		(1)
$\Rightarrow P_1$	{(1)}	(2)
$\Rightarrow P_2$	$\{(1)\}$	(3)
$\Rightarrow P_3$	$\{(1)\}$	(4)
$\Rightarrow P_4$	$\{(1)\}$	(5)
$\Rightarrow Q_1 \land Q_2$	$\{(2) \text{ and hints for } P_1 \Rightarrow Q_1 \land Q_2\}$	(6)
$\Rightarrow Q_1$	{(6)}	(7)
$\Rightarrow Q_2$	{(6)}	(8)
$\Rightarrow \exists x$	/* begin scope $\exists x */$	
Q_3	$\{(3), (8), \text{ and hints for } Q_2 \land P_2 \Rightarrow (\exists x.Q_3)\}$	(9)
$\Rightarrow Q_4$	$\{(4), (9), \text{ and hints for } Q_3 \land P_3 \Rightarrow Q_4\}$	(10)
$\Rightarrow Q_5$	$\{(4), (9), \text{ and hints for } Q_3 \land P_3 \Rightarrow Q_5\}$	(11)
\Rightarrow $R_1 \lor R_2$	$\{R_1 \lor R_2 \text{ is a tautology}\}$	(12)
case 1: R_1	/* case split on (12) */	(13)
$\Rightarrow Q_6$	$\{(5), (10), (13), \text{ and hints for } Q_4 \land R_1 \land P_4 \Rightarrow Q_6\}$	(14)
case 2: R_2	/* case split on (12) */	(15)
$\Rightarrow Q_6$	$\{(5), (11), (15), \text{ and hints for } Q_5 \land R_2 \land P_4 \Rightarrow Q_6\}$	(16)
$\Rightarrow Q_6$	/* combine cases 1 and 2 */	(17)
$\Rightarrow Q_7$	{(7), (17), and hints for $(Q_1 \land \exists x. Q_6) \Rightarrow Q_7$ }	(18)

Fig. 2: A proof of a scheduling theorem in the style with labels to refer to subformulae.

3.2 Mutual exclusion

Since there is only one processor, if one task is running, then any other task cannot be running:

$$A_2 \cong \bigwedge_{i=1}^m \Box ([\operatorname{Run}_i] \Longrightarrow \bigwedge_{i \neq i} [\neg \operatorname{Run}_i]).$$

In other words, there does not exist an interval such that two tasks are running in parallel.

LEMMA 1. For any *i* and *j*, $i \neq j$, $A_2 \Rightarrow \Box(\neg [Run_i \land Run_j])$.

PROOF. From DC25, we only need to prove $A_2 \Rightarrow \neg [\operatorname{Run}_i \land \operatorname{Run}_j]$, and this follows immediately from DC11 and propositional logic. \Box

Consider a subset of tasks $\tau_{i_1}, \ldots, \tau_{i_n}$ $(n \le m)$. The single processor assumption implies that the sum of the running time of these tasks is equal to $\int \bigvee_{j=1}^{n} \operatorname{Run}_{i_j}$.

Lemma 2. $A_2 \Rightarrow \Box (\sum_{j=1}^n \int Run_{i_j} = \int \bigvee_{j=1}^n Run_{i_j}).$

PROOF. By DC25 it is enough to prove $A_2 \Rightarrow (\sum_{j=1}^n \int \operatorname{Run}_{i_j} = \int \bigvee_{j=1}^n \operatorname{Run}_{i_j})$. This is shown as follows:

$$A_{2} \qquad (1)$$

$$\Rightarrow \sum_{j=1}^{n-1} \int (\operatorname{Run}_{i_{j}} \wedge \operatorname{Run}_{i_{n}}) = 0 \qquad \{\operatorname{Lemma 1 and DC20}\} \qquad (2)$$

$$\Rightarrow \int \sqrt{\sum_{j=1}^{n-1} (\operatorname{Run}_{i_j} \wedge \operatorname{Run}_{i_n})} \leq \sum_{j=1}^{n-1} \int (\operatorname{Run}_{i_j} \wedge \operatorname{Run}_{i_n})$$
 {DCA4} (3)

$$\Rightarrow \int \bigvee_{j=1}^{n-1} (\operatorname{Run}_{i_j} \wedge \operatorname{Run}_{i_n}) = 0 \qquad \{(2), (3), \text{ and DCA3}\} \qquad (4)$$
$$\Rightarrow \int \bigvee_{n=1}^{n} (\operatorname{Run}_{i_j} - (\int \bigvee_{n=1}^{n-1} \operatorname{Run}_{i_j}) + (\operatorname{Run}_{i_j} - (\int \bigvee_{n=1}^{n-1} \operatorname{Run}_{i_j}) \wedge (\operatorname{Run}_{i_j}) = (\int \bigcup_{n=1}^{n-1} \operatorname{Run}_{i_j}) + (\int \bigcup_{n=1}^{n-1} \operatorname{Run}_{i_j}) = (\int \bigcup_{n=1}^{n-1} \operatorname{Run}_{i_j}) = (\int \bigcup_{n=1}^{n-1} \operatorname{Run}_{i_j}) + (\int \bigcup_{n=1}^{n-1} \operatorname{Run}_{i_j}) = (\int \bigcup_{n=1}^{$$

$$\Rightarrow \int \bigvee_{j=1}^{n} \operatorname{Run}_{i_j} = \left(\int \bigvee_{j=1}^{n-1} \operatorname{Run}_{i_j} \right) + \int \operatorname{Run}_{i_n} - \int \left(\left(\bigvee_{j=1}^{n-1} \operatorname{Run}_{i_j} \right) \wedge \operatorname{Run}_{i_n} \right) \quad \{ \text{DCA4} \}$$
(5)

$$\Rightarrow \int ((\bigvee_{j=1}^{n-1} \operatorname{Run}_{i_j}) \wedge \operatorname{Run}_{i_n}) = \int \bigvee_{j=1}^{n-1} (\operatorname{Run}_{i_j} \wedge \operatorname{Run}_{i_n})$$
 {DCA6} (6)

$$\Rightarrow \int \bigvee_{j=1}^{n} \operatorname{Run}_{i_j} = \left(\int \bigvee_{j=1}^{n-1} \operatorname{Run}_{i_j} \right) + \int \operatorname{Run}_{i_n}$$
 (4), (5), and (6)} (7)

We can repeat the above steps until the lemma is proven. \Box

Two obvious facts can be easily derived from this lemma: the sum of the running time of a subset of tasks is less than or equal to the length of the interval, and the equality holds if the processor is occupied completely by the tasks over the interval.

Corollary 1 of Lemma 2.
$$A_2 \Rightarrow \Box (\sum_{j=1}^n \int \operatorname{Run}_{i_j} \leq \ell).$$

COROLLARY 2 OF LEMMA 2.
$$A_2 \Rightarrow \Box (\lceil \bigvee_{j=1}^n \operatorname{Run}_{i_j} \rceil \Rightarrow (\sum_{j=1}^n \int \operatorname{Run}_{i_j} = \ell)).$$

3.3 No overhead

We assume that if there are some tasks with standing requests, then one of the tasks must be running:

$$A_3 \cong \Box(\lceil \bigvee_{i=1}^m \operatorname{Std}_i \rceil \Rightarrow \lceil \bigvee_{i=1}^m \operatorname{Run}_i \rceil).$$

3.4 Execution time bound

Task τ_i requires C_i units execution time for each of its period T_i , and in the interval of length ℓ starting from 0, there are at most $\lceil \ell/T_i \rceil$ requests for τ_i . Consequently, the accumulated running time of the task will not exceed $\lceil \ell/T_i \rceil C_i$:

$$A_4 \cong \bigwedge_{i=1}^m \square_p \left(\int \operatorname{Run}_i \leq \lceil \ell/T_i \rceil C_i \right).$$

Let $mult_i \cong \exists k \in \mathbb{N}.(k \cdot T_i = \ell).$

Thus, *mult_i* holds for intervals whose lengthes are multiples of period T_i . If the request of task τ_i is still not fulfilled at a time point and it is not a period point, then the accumulated running time up to that moment cannot be equal to (should be less than) $\lceil \ell/T_i \rceil C_i$:

$$A_5 \cong \bigwedge_{i=1}^m \Box_p \neg (((\neg mult_i) \land (\int \operatorname{Run}_i = \lceil \ell/T_i \rceil C_i)) \cap [\operatorname{Std}_i]).$$

If a task's request is not standing, then the execution time requirement has been reached:

$$A_6 \stackrel{\simeq}{=} \bigwedge_{i=1}^m \Box_p \left((tt \uparrow \neg \mathsf{Std}_i \rceil) \Rightarrow \left(\int \mathsf{Run}_i = \lceil \ell / T_i \rceil C_i \right) \right).$$

Denote the conjunction of all the assumptions A_1 to A_6 by A,

$$A \widehat{=} A_1 \wedge A_2 \wedge A_3 \wedge A_4 \wedge A_5 \wedge A_6$$

It represents the general assumptions about behaviours of the scheduling algorithms that we study.

3.5 Requirement

In any interval starting from 0 and of length ℓ , a task should have been granted at least $\lfloor \ell/T_i \rfloor C_i$ execution time. The requirement for task τ_i is

$$Req_i \cong \Box_p(\int \operatorname{Run}_i \ge \lfloor \ell/T_i \rfloor C_i).$$

This must hold for every task:

$$Req \cong \bigwedge_{i=1}^{m} Req_i.$$

3.6 Necessary condition

If the tasks are schedulable, then the running time requirement is satisfied over any interval, and therefore in particular over [0, T], where $T = T_1 T_2 \cdots T_n$ is the product of the periods of all the tasks. The necessity of the condition is implied by the following theorem.

Theorem 1. $(A \land Req \land (\ell = T)) \Rightarrow (\sum_{i=1}^{m} C_i/T_i \le 1).$

Proof.

$A \wedge Req \wedge (\ell = T)$		(1)
$\Rightarrow A$	{(1)}	(2)
$\Rightarrow Req$	{(1)}	(3)
$\Rightarrow \ell = T$	{(1)}	(4)
$\Rightarrow \bigwedge_{1 \le i \le m} (\int \operatorname{Run}_i \ge \lfloor \ell / T_i \rfloor C_i)$	{definition of <i>Req</i> , DC7, DC8, and (3)}	(5)
$\Rightarrow \bigwedge_{1 \le i \le m} (\int \operatorname{Run}_i \ge (T/T_i)C_i)$	$\{(4) \text{ and } (5)\}$	(6)
$\Rightarrow \sum_{i=1}^{m} \int \operatorname{Run}_i \ge \sum_{i=1}^{m} (T/T_i) C_i$	{(6)}	(7)
$\Rightarrow \ell \ge \sum_{i=1}^{m} (T/T_i)C_i$	{Corollary 1 of Lemma 2, and (7)}	(8)
$\Rightarrow \sum_{i=1}^{m} C_i / T_i \le 1$	$\{(4) \text{ and } (8)\}$	(9)

4. Static Scheduler

Without loss of generality, we assume priorities are in decreasing order from τ_1 to τ_m . For i < j, task τ_j cannot be running if task τ_i has a standing request, i.e.

$$Sch_S \cong \bigwedge_{1 \le i \le m} \Box([Std_i] \Rightarrow \bigwedge_{i < j \le m} [\neg Run_j]).$$

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4.1 General properties

For any task τ_k , if its execution time is not fulfilled at *t* within its first period, then the interval [0, t] is completely occupied by τ_1, \ldots, τ_k .

LEMMA 3. For any $1 \le k \le m$,

$$A_3 \wedge A_5 \wedge A_6 \wedge Sch_S \Rightarrow \Box_p \left(\left(\left(\ell \le T_k \right) \wedge \left(tt^{\widehat{}} Std_k \right) \right) \right) \Rightarrow \left[\bigvee_{i=1}^k Run_i \right] \right).$$

PROOF. According to DC26 and propositional logic, it is enough to prove

$$(A_3 \wedge A_5 \wedge A_6 \wedge Sch_S \wedge (\ell \leq T_k) \wedge (tt^{\mathsf{T}}\mathrm{Std}_k])) \Rightarrow [\bigvee_{i=1}^k \mathrm{Run}_i].$$

This is shown as follows:

$A_3 \wedge A_5 \wedge A_6 \wedge Sch_S \wedge (\ell \leq T_k) \wedge (tt^{T}Std_{k}))$		(1)
$\Rightarrow A_3 \wedge A_5 \wedge A_6$	{(1)}	(2)
$\Rightarrow \ell \leq T_k$	{(1)}	(3)
$\Rightarrow tt [Std_k]$	{(1)}	(4)
$\Rightarrow (\int Std_k = \ell) \lor (\int Std_k \neq \ell)$	{tautology}	(5)
case 1: $\int Std_k = \ell$	{case split on (5)}	(6)
$\Rightarrow \ell > 0$	{(4)}	(7)
$\Rightarrow [Std_k]$	{(6) and (7)}	(8)
case 2: $\int \operatorname{Std}_k \neq \ell$	{case split on (5)}	(9)
\Rightarrow $tt [\neg Std_k] tt$	{(9) and DC20}	(10)
$\Rightarrow tt^{T}Std_{k}^{T}Std_{k}^{T}$	{(10) and DC14}	(11)
$\Rightarrow tt [\neg Std_k] (\ell > 0)$	{(11)}	(12)
$\Rightarrow (\int \operatorname{Run}_k = C_k)^{}(\ell > 0)$	$\{(3), (12), \text{ and } A_6\}$	(13)
$\Rightarrow ((\ell < T_k) \land (\int \operatorname{Run}_k = C_k)) \cap [\operatorname{Std}_k]$	$\{(3), (4), \text{ and } (13)\}$	(14)
$\Rightarrow ((\neg mult_k) \land (\ell < T_k) \land (\int \operatorname{Run}_k = C_k))$) $TStd_k$ {(14)}	(15)
\Rightarrow ff	$\{(15) \text{ and } A_5\}$	(16)
$\Rightarrow \lceil \operatorname{Std}_k \rceil$	{combine cases 1 and 2}	(17)
$\Rightarrow \lceil \bigvee_{i=1}^{m} \operatorname{Run}_i \rceil$	$\{(17) \text{ and } A_3\}$	(18)
$\Rightarrow \wedge_{i=k+1}^{m} \lceil \neg \operatorname{Run}_i \rceil$	$\{(17) \text{ and } Sch_S\}$	(19)
$\Rightarrow \lceil \bigvee_{i=1}^{k} \operatorname{Run}_{i} \rceil$	{(18), (19), and DC11}	(20)

We next prove a result similar to Liu and Layland's critical instance theorem: a task can be scheduled successfully by the static scheduler if it can be done so in its first period. In another word, the task set is schedulable by the static scheduler if the tasks can be scheduled successfully in the first longest period.

THEOREM 2. For any $1 \le i \le m$,

$$(A \land Sch_S) \Rightarrow (Req_i \Leftrightarrow \Box_p((\ell \ge T_i) \Rightarrow (((\ell = T_i) \land Req_i)^{\uparrow}tt))).$$

PROOF. For any $1 \le i \le m$, it is obvious that

$$Req_i \Rightarrow \Box_p((\ell \ge T_i) \Rightarrow (((\ell = T_i) \land Req_i)^{\uparrow}tt)),$$

therefore we only need to prove

$$(A \land Sch_S \land \Box_p((\ell \ge T_i) \Rightarrow (((\ell = T_i) \land Req_i)^{tt}))) \Rightarrow Req_i,$$

and by DC26 it is reduced to show

$$(A \land Sch_S \land \Box_p((\ell \ge T_i) \Rightarrow (((\ell = T_i) \land Req_i)^{t}))) \Rightarrow (\int \operatorname{Run}_i \ge \lfloor \ell/T_i \rfloor C_i).$$

Suppose that there exists a *k* such that $\int \operatorname{Run}_k < \lfloor \ell / T_k \rfloor \cdot C_k$, then we prove this leads to contradiction:

$$\begin{split} A \wedge Sch_{S} \wedge \Box_{p}((\ell \geq T_{k}) \Rightarrow (((\ell = T_{k}) \wedge Req_{k})^{-}tt)) \wedge \int \mathbb{R}un_{k} < \lfloor \ell/T_{k} \rfloor \cdot C_{k} & (1) \\ \Rightarrow A & (1) \} & (2) \\ \Rightarrow Sch_{S} & (1) \} & (3) \\ \Rightarrow \Box_{p}((\ell \geq T_{k}) \Rightarrow (((\ell = T_{k}) \wedge Req_{k})^{-}tt)) & \{(1)\} & (4) \\ \Rightarrow \int \mathbb{R}un_{k} < \lfloor \ell/T_{k} \rfloor C_{k} & (1) \} & (5) \\ \Rightarrow (\ell \geq T_{k}) \Rightarrow (((\ell = T_{k}) \wedge Req_{k})^{-}tt) & \{(4) \text{ and DC8}\} & (6) \\ \Rightarrow \ell \geq T_{k} \wedge C_{k} > 0 & \{(5) \text{ and DCA3}\} & (7) \\ \Rightarrow ((\ell = T_{k}) \wedge (\int \mathbb{R}un_{k} = C_{k}))^{-}tt & \{(8), (2), \text{ def. of } Req_{k}, A_{4}, \text{ and DC8}\} & (9) \\ \Rightarrow ((\ell = T_{k}) \wedge (\int \mathbb{R}un_{k} = C_{k}) \wedge (tt^{-} \mathbb{R}un_{k}]^{-} (\int \mathbb{R}un_{k} = 0))^{-}tt & (10) \\ & = \{(\ell = T_{k}) \wedge (\int \mathbb{R}un_{k} = C_{k}) \wedge (tt^{-} \mathbb{R}un_{k}]^{-} (fun_{k} = 0))^{-}tt & (10) \\ & = ((\ell = T_{k}) \wedge (\int \mathbb{R}un_{k} = C_{k}) \wedge (((\ell = a) \wedge (tt^{-} \mathbb{R}un_{k}]))^{-} \\ & ((\ell = T_{k}) \wedge (\int \mathbb{R}un_{k} = C_{k}) \wedge (((\ell = a) \wedge (tt^{-} \mathbb{R}un_{k}]))^{-} \\ & (\int \mathbb{R}un_{k} = 0))^{-}tt & \{(11), (3), \operatorname{ITL7}, \operatorname{Lemma 3}, \operatorname{and DC45}\} & (12) \\ \Rightarrow ((\ell = a) \wedge (a \leq T_{k}) \wedge (\ell > 0) \wedge (\ell = \sum_{i=1}^{k} \int \mathbb{R}un_{i}] \\ & \wedge \bigwedge_{i=1}^{k} (\int \mathbb{R}un_{i} = \lceil \ell/T_{i} \rceil \cap 1)^{-}tt & \{(12), \operatorname{Corollary 2}, A_{6}, \operatorname{and DC1}\} & (13) \\ \Rightarrow (a \leq T_{k}) \wedge (a > 0) \wedge (a = \sum_{i=1}^{k} \lceil a/T_{i} \rceil \cap 1)^{-}tt & \{(14) \text{ and ITL4}\} & (15) \\ \Rightarrow (\int \bigvee_{i=1}^{k} \mathbb{R}un_{i} = \ell) \vee (\int \bigvee_{i=1}^{k} \mathbb{R}un_{i} \neq \ell) & \{\operatorname{tautology}\} & (16) \\ \end{split}$$

case 1: $\int \bigvee_{i=1}^{k} \operatorname{Run}_{i} = \ell$ $\{\text{case split on } (16)\}\$ (17) $\Rightarrow \exists n \in \mathbb{N}, b \in \mathbb{R}. \ 0 \le b < a \land \ell = na + b$ /* begin scope $\exists n, b * / (18)$ $((\ell = na) \land (\int \bigvee_{i=1}^{k} \operatorname{Run}_{i} = \ell)) (\ell = b)$ \Rightarrow (19){(17), (18), ITL7, and DC14} $((\ell = na) \land (\sum_{i=1}^{k} \int \operatorname{Run}_{i} = \ell)) (\ell = b)$ \Rightarrow $\{(19) \text{ and Lemma } 2\}$ (20) $(\bigwedge_{i=1}^{k-1} (\int \operatorname{Run}_i \leq \lceil na/T_i \rceil C_i))^{\widehat{}} (\ell = b)$ $\{A_4\}$ (21) ⇒ $|\ell/T_k| \leq \lceil na/T_k \rceil + \lfloor b/T_k \rfloor$ $\{(18)\}\ (22)$ \Rightarrow $\lfloor \ell/T_k \rfloor \leq \lceil na/T_k \rceil$ $\{(22) \text{ and } b < T_k\}$ (23) \Rightarrow $\int \operatorname{Run}_k < \lceil na/T_k \rceil C_k$ ⇒ {(5) and (23)} (24) $(\int \operatorname{Run}_k < \lceil na/T_k \rceil C_k)^{(\ell = b)}$ {(18), (24), ITL7, and DC15} (25) \Rightarrow $(na < \sum_{i=1}^{k} \lceil na/T_i \rceil C_i)^{(\ell = b)}$ {(20), (21), (25), and DC16} (26) \Rightarrow $na < \sum_{i=1}^{k} \lceil na/T_i \rceil C_i$ {(26) and ITL4} (27) \Rightarrow $na = n \sum_{i=1}^{k} \lceil a/T_i \rceil C_i$ \Rightarrow {(15)} (28) $n\sum_{i=1}^{k} \lceil a/T_i \rceil C_i < \sum_{i=1}^{k} \lceil na/T_i \rceil C_i$ {(27) and (28)} (29) \Rightarrow $\{(29) \text{ and arithmetics}\}$ (30) \Rightarrow ff $\Rightarrow ff$ /* end scope $\exists n, b * / (31)$ case 2: $\int \bigvee_{i=1}^{k} \operatorname{Run}_{i} \neq \ell$ $\{\text{case split on } (16)\}$ (32) \Rightarrow $tt ([\land_{i=1}^{k} \neg \operatorname{Run}_{i}] ([\land_{i=1}^{k} \operatorname{Run}_{i} = \ell])$ {(32) and DC20} (33) $\Rightarrow tt (\bigwedge_{i=1}^{k} \neg \text{Std}_{i}) ((\bigwedge_{i=1}^{k} \text{Run}_{i} = \ell)$ $\{(33), (3), A_3\}$ (34) $\Rightarrow (\bigwedge_{i=1}^{k} \int \operatorname{Run}_{i} = \lceil \ell/T_{i} \rceil C_{i}) \widehat{} (\int \bigvee_{i=1}^{k} \operatorname{Run}_{i} = \ell)$ $\{(34) \text{ and } A_6\}$ (35) $\Rightarrow \exists n' \in \mathbb{N}, b' \in \mathbb{R}. \ 0 \le b' < a \land$ /* begin scope $\exists n', b' */$ $(\bigwedge_{i=1}^{k} \int \operatorname{Run}_{i} = \lceil \ell/T_{i} \rceil C_{i}) \widehat{} (\ell = n'a + b') \wedge (\int \bigvee_{i=1}^{k} \operatorname{Run}_{i} = \ell)) \quad \{(35)\} \quad (36)$ $tt^{(\ell = n'a)} \wedge (\int_{i=1}^{k} \operatorname{Run}_{i} = \ell)^{(\ell = b')}$ $\{(36) \text{ and } DC14\}$ (37) \Rightarrow $tt^{(\ell = n'a)} \wedge (\sum_{i=1}^{k} \int \operatorname{Run}_{i} = \ell)^{(\ell = b')}$ \Rightarrow $\{(37) \text{ and Lemma } 2\}$ (38) $(\bigwedge_{i=1}^{k-1} (\int \operatorname{Run}_i \leq \lceil \ell/T_i \rceil C_i))^{(\ell)} = b')$ $\{(38), A_4 \text{ and } DC6\}\ (39)$ ⇒ $tt^{(\ell)}(\ell = n'a) \land (\bigwedge_{i=1}^{k-1} (\int \operatorname{Run}_i \le \lceil \ell/T_i \rceil C_i)))^{(\ell)}(\ell = b')$ \Rightarrow {(36), (39) and DC22} (40) $tt^{(\ell)}(\ell = n'a + b') \land (\int \operatorname{Run}_k < \lfloor \ell/T_k \rfloor C_k))$ {(5), (36) and DC23} (41) \Rightarrow $\{\text{similar to steps } (22) - (30)\}\$ (42) ff $\{\text{combine cases 1 and 2}\}$ (43) ff/* end scope $\exists a */(44)$ $\Rightarrow ff$

We have hence deduced a contradiction. This completes the proof of the theorem.

 \Rightarrow

4.2 RM scheduler

Recall we adopt the convention that priorities are in decreasing order from τ_1 to τ_m . The RM scheduler is then specified as

 $Sch_{RM} \cong Sch_S \wedge (T_1 \leq T_2 \leq \cdots \leq T_m).$

An important concept used in Liu and Layland's proof is that of *full utilisation*. A set of tasks is said to fully utilise the processor if the task set is schedulable and any increase of the execution time for any task will cause the task set to be unschedulable. Liu and Layland, as well as most of the subsequent work, including recent papers such as [Devillers and Goossens 2000,Goossens 1999], did not further formalise the concept. Reasoning with this kind of definition is inevitably at a lower level of formality.

We studied a formal definition in [Dong *et al.* 1999], and in the proofs followed we found that the property that the task set is schedulable is not useful. We therefore did not include that property, but still used the term full utilisation in [Dong *et al.* 1999], although it is more appropriate to give it another name which we do now.

DEFINITION 1. A set of tasks τ_1 , τ_2 ,..., τ_m , with execution times C_1 , C_2 ,..., C_m and periods T_1 , T_2 ,..., T_m , is said to have non-increasable execution time, denoted as $non_inc(C_1, \dots, C_m, T_1, \dots, T_m)$, iff for any $0 < x \leq T_{max}$, $\sum_{i=1}^m \lceil x/T_i \rceil C_i \geq x$.

At any time point x, $\sum_{i=1}^{m} \lceil x/T_i \rceil C_i$ is the total requested execution time of all the tasks until that moment. We can prove that *non_inc* implies that the processor cannot be idle in the interval $[0, T_m]$, and consequently any increase of C_i will make the task set unschedulable by RM (in particular, τ_m will miss its deadline). However, we do not include the proofs since the results are not needed for the theorems concerned in this paper.

Denote (C_1, \dots, C_m) by C and (T_1, \dots, T_m) by T. Denote $non_inc(C_1, \dots, C_m, T_1, \dots, T_m)$ by $non_inc(C, T)$. Similarly, let C' stand for (C'_1, \dots, C'_m) , T' for (T'_1, \dots, T'_m) , we shall abbreviate $non_inc(C'_1, \dots, C'_m, T_1, \dots, T_m)$ as $non_inc(C', T)$ and $non_inc(C'_1, \dots, C'_m, T'_1, \dots, T'_m)$ as $non_inc(C', T)$ and $non_inc(C'_1, \dots, C'_m, T'_1, \dots, T'_m)$ as $non_inc(C', T)$.

Let lub(m) denote the minimum of the utilisation factors over all the sets of m tasks that have non-increasable execution time. Formally,

DEFINITION 2. $lub(m) \cong \min\{\sum_{i=1}^{m} C_i/T_i \mid non_inc(C, T)\}.$

The value of lub(m) for RM was discovered by Liu and Layland [Liu and Layland 1973] and is expressed by the following lemma. The calculation involves many technical details, and a corrected and improved proof is given in the appendix.

LEMMA 4. For RM, $lub(m) = m(2^{\frac{1}{m}} - 1)$.

The below fact follows from the property of the function.

Corollary 3 of Lemma 4. $lub(k) \ge lub(m)$ if $k \le m$.

The value of lub(m) obviously provides an upper bound for the set of *m* tasks, in the sense that if its utilisation factor is above the value, then it is quite possible that the task set is unschedulable (whether the task set is schedulable depends on the specific values of execution times and periods). The question is whether lub(m) also provides the lower bound, that is, for any given set of *m* tasks, if its utilisation factor is less than lub(m), then the task set is schedulable. Liu and Layland found this to be true, but just stated it without proof [Liu and Layland 1973].

However, this property does not follow from the definition directly and as far as we know was only proved recently by Devillers and Goossens [Devillers and Goossens 2000] and us [Dong *et al.* 1999] independently. ²

Theorem 3. (Sufficiency for RM) $(A \wedge Sch_S \wedge (\sum_{i=1}^m C_i/T_i \leq lub(m))) \Rightarrow Req.$

Proof.

$A \wedge Sch_S \wedge (\sum_{i=1}^m C_i/T_i \le lub(m)) \wedge \neg Req_k$	(1)
$\Rightarrow A \qquad \{(1)\}$	(2)
$\Rightarrow Sch_S \tag{(1)}$	(3)
$\Rightarrow \sum_{i=1}^{m} C_i / T_i \le lub(m) $ ^{{(1)}	(4)
$\Rightarrow \neg Req_k $ {(1)}	(5)
$\Rightarrow ((\ell = T_k) \land (\int \operatorname{Run}_k < C_k))^{}tt \qquad \{(2), (3) \text{ and Theorem 2}\}$	(6)
$\Rightarrow ((\ell = T_k) \land (\int \operatorname{Run}_k < C_k) \land (tt \cap [\operatorname{Std}_k])) \cap tt \qquad \{(2) \text{ and } (6)\}$	(7)
$\Rightarrow ((\ell = T_k) \land \lceil \bigvee_{i=1}^k \operatorname{Run}_i \rceil \land (\int \operatorname{Run}_k < C_k))^{-tt}$	(8)
{(2), (3), (7) and Lemma 3}	
$\Rightarrow \exists C'_k. 0 \le C'_k < C_k \land \qquad /* \text{ formulae below are within } \exists */$	
$\Rightarrow ((\ell = T_k) \land \lceil \bigvee_{i=1}^k \operatorname{Run}_i \rceil \land (\int \operatorname{Run}_k = C'_k)) \cap tt \qquad \{(8) \text{ and } \operatorname{DC10}\}$	(9)
$\Rightarrow \forall x.0 < x \le T_k \Rightarrow \qquad /* \text{ formulae below are within } \forall */$	
$\Rightarrow \qquad (\ell = T_k) \Rightarrow ((\ell = x)^{}(\ell = T_k - x)) \qquad \text{{ITL7}}$	(10)
$\Rightarrow \qquad (((\ell = x)^{(\ell)} = T_k - x)) \land [\bigvee_{i=1}^k \operatorname{Run}_i] \land (\int \operatorname{Run}_k = C'_k))^{tt}$	(11)
{(9) and (10)}	
$\Rightarrow \qquad ((\ell = x) \land \lceil \bigvee_{i=1}^{k} \operatorname{Run}_{i} \rceil \land (\int \operatorname{Run}_{k} \leq C'_{k}))^{\frown} tt$	(12)
{(11), DC14 and DC15}	
$\Rightarrow \qquad ((\ell = x) \land (\ell = \sum_{i=1}^{k} \int \operatorname{Run}_{i}) \land (\int \operatorname{Run}_{k} \le C'_{k}))^{-}tt$	(13)
{(12), DC13 and Corollary 2}	
$\Rightarrow \qquad (x \le (\sum_{i=1}^{k-1} \lceil x/T_i \rceil C_i) + C'_k)^{-tt} \qquad \{(2) \text{ and } (13)\}$	(14)
$\Rightarrow \qquad x \le \left(\sum_{i=1}^{k-1} \lceil x/T_i \rceil C_i\right) + C'_k \qquad \{(14) \text{ and } ITL4\}$	(15)

 $^{^2}$ Liu and Layland's statement was of course given using full utilisation and Devillers and Goossens proved that. Although we used the term full utilisation in [Dong *et al.* 1999], the actual definition was non-increasable execution time.

\Rightarrow	$non_inc(C_1,\cdots,C_{k-1},C'_k,T_1,\cdots,T_k)$	{(15) and the def. of <i>non_inc</i> }	(16)
\Rightarrow	$lub(k) \leq (\sum_{i=1}^{k-1} C_i/T_i) + C'_k/T_k$	$\{(16) \text{ and the def. of } lub(k)\}\$	(17)
\Rightarrow	$(\sum_{i=1}^{k-1} C_i / T_i) + C'_k / T_k < \sum_{i=1}^m C_i / T_i$	$\{C'_k < C_k \text{ and } k \le m\}$	(18)
\Rightarrow	lub(k) < lub(m)	{(4), (17) and (18)}	(19)
\Rightarrow	$f\!f$	{(19) and Cor. of Lemma 4}	(20)
$\Rightarrow f$	f	{(20)}	(21)

This completes the proof for the theorem. \Box

5. Proof for EDF

EDF assigns priorities to tasks dynamically according to the distance to their deadlines. The task closer to the deadline has a higher priority.

The following formula describes that at least in the latter part of the considered interval, task τ_i is more urgent than task τ_i :

$$\operatorname{urgent}(i, j) \widehat{=} \lceil \ell/T_i \rceil T_i < \lceil \ell/T_i \rceil T_j.$$

The subinterval on which task τ_i is more urgent than task τ_j may be very small or it may be the whole interval. Once such a subinterval exists, and task τ_j is running over it, then task τ_i cannot have a standing request:

$$Sch_{EDF} \cong \Box_p (((tt [Run_i]) \land urgent(i, j)) \Rightarrow (tt [\neg Std_i])).$$

As for EDF, Liu and Layland discovered that for a task set to be scheduable, it is sufficient that its utilisation factor is not greater than 1 (this is of course also the necessary condition, proven formally in Section 3.6, as for all the scheduling policies).

Theorem 4. (Sufficiency for EDF) $(A \wedge Sch_{EDF} \wedge (\sum_{i=1}^{m} C_i/T_i \leq 1)) \Rightarrow Req.$

The proof is by contradiction. Suppose that the requirement is not satisfied, then there exists k,

$$\diamond_p \left(\int \operatorname{Run}_k < \lfloor \ell / T_k \rfloor C_k \right).$$

We shall deduce that $\sum_{i=1}^{m} C_i/T_i > 1$. We first prove the following lemma.

Lemma 5.
$$A_2 \Rightarrow \Box \left(\left(\left(\bigwedge_{i=1}^m (\int Run_i \le \lfloor \ell/T_i \rfloor C_i) \right) \land \left(\int Run_k < \lfloor \ell/T_k \rfloor C_k \right) \land \left(\int \bigvee_{i=1}^m Run_i = \ell \right) \right) \Rightarrow \left(\sum_{i=1}^m C_i/T_i > 1 \right) \right).$$

By DC25, we only need to prove

$$A_2 \Rightarrow (((\bigwedge_{i=1}^m (\int \operatorname{Run}_i \le \lfloor \ell/T_i \rfloor C_i)) \land (\int \operatorname{Run}_k < \lfloor \ell/T_k \rfloor C_k) \land (\int \bigvee_{i=1}^m \operatorname{Run}_i = \ell)) \Rightarrow (\sum_{i=1}^m C_i/T_i > 1)).$$

Proof.

$$A_{2} \wedge (\bigwedge_{i=1}^{m} (\int \operatorname{Run}_{i} \leq \lfloor \ell/T_{i} \rfloor C_{i})) \wedge (\int \operatorname{Run}_{k} < \lfloor \ell/T_{k} \rfloor C_{k}) \wedge (\int \bigvee_{i=1}^{m} \operatorname{Run}_{i} = \ell)$$
(1)

$$\Rightarrow (\bigwedge_{i=1}^{m} (\int \operatorname{Run}_{i} \leq \lfloor \ell/T_{i} \rfloor C_{i})) \wedge (\int \operatorname{Run}_{k} < \lfloor \ell/T_{k} \rfloor C_{k}) \wedge (\sum_{i=1}^{m} \int \operatorname{Run}_{i} = \ell)$$
(2)
{Lemma 2}

$$\Rightarrow \sum_{i=1}^{m} \lfloor \ell/T_i \rfloor C_i > \ell \tag{3}$$

$$\Rightarrow \sum_{i=1}^{m} C_i / T_i > 1 \tag{4}$$

Now, we come to the proof for Theorem 4. Let

$$\alpha(i) \stackrel{\frown}{=} mult_{i}^{\frown}((\ell < T_{i}) \land (\int \operatorname{Run}_{i} = 0)), \tag{1}$$

$$\beta(i) \stackrel{\frown}{=} mult_i((\ell < T_i) \land (\int \operatorname{Run}_i \neq 0)).$$
⁽²⁾

Proof.

01.		
$A \wedge Sch_{EDF} \wedge \diamondsuit_p \left(\int \operatorname{Run}_k < \lfloor \ell/T_k \rfloor C_k \right)$		(3)
$\Rightarrow \diamondsuit_p \left(\int \operatorname{Run}_k < \lfloor \ell / T_k \rfloor C_k \right)$	{ (3) }	(4)
$\Rightarrow \exists n \in \mathbb{N}, \exists r \in \mathbb{R}.0 \le r < T_k \land ((\int \operatorname{Run}_k < \lfloor \ell / T_k \rfloor C))$	$(\mathcal{L}_k) \wedge (\ell = nT_k + r))^{-}tt$	(5)
$\Rightarrow \diamond_p$ /* formula	ae below are within $\diamondsuit_p * /$	
$(\int \operatorname{Run}_k < \lfloor \ell / T_k \rfloor C_k) \land mult_k $	(5), DC1 and def. of \diamond_p }	(6)
$\Rightarrow \int \operatorname{Run}_k < \lfloor \ell/T_k \rfloor C_k$	{(6)}	(7)
\Rightarrow mult _k	{(6)}	(8)
$\Rightarrow \bigwedge_{i=1}^{m} (\alpha(i) \lor \beta(i))$	{ (1) and (2)}	(9)
$\Rightarrow (\bigvee_{i=1}^{m} \beta(i)) \lor (\bigwedge_{i=1}^{m} \neg \beta(i))$	{tautology}	(10)
case 1 : $\bigwedge_{i=1}^{m} \neg \beta(i)$	{case split on (10)}	(11)
$\Rightarrow \bigwedge_{i=1}^{m} \alpha(i)$	{(9) and (11)}	(12)
$\Rightarrow \bigwedge_{i=1}^{m} (\int \operatorname{Run}_{i} \leq \lfloor \ell/T_{i} \rfloor C_{i})$	$\{A_4, (12), \text{ and } (1)\}$	(13)
$\Rightarrow (\int \bigvee_{i=1}^{m} \operatorname{Run}_{i} = \ell) \lor (\int \bigvee_{i=1}^{m} \operatorname{Run}_{i} \neq \ell)$	{tautology}	(14)
case 1.1 : $\int \bigvee_{i=1}^{m} \operatorname{Run}_{i} = \ell$	{case split on (14)}	(15)
$\Rightarrow \sum_{i=1}^{m} C_i / T_i > 1 \qquad \{(7), ($	13), (15), and Lemma 5}	(16)
case 1.2: $\int \bigvee_{i=1}^{m} \operatorname{Run}_{i} \neq \ell$	{case split on (14)}	(17)
$\Rightarrow tt^{(m)} \wedge_{i=1}^{m} \neg \operatorname{Run}_{i}^{(m)} (\int \bigvee_{i=1}^{m} \operatorname{Run}_{i} = \ell)$	$\{(17) \text{ and } DC20\}$	(18)
$\Rightarrow tt \left(\bigwedge_{i=1}^{m} \neg \operatorname{Std}_{i} \right) \left(\left(\bigvee_{i=1}^{m} \operatorname{Run}_{i} = \ell \right) \right)$	$\{(18) \text{ and } A_3\}$	(19)
$\Rightarrow (\bigwedge_{i=1}^{m} \int \operatorname{Run}_{i} = \lceil \ell/T_{i} \rceil C_{i})^{(m)} (\int \bigvee_{i=1}^{m} \operatorname{Run}_{i}$	$\mathbf{h}_i = \ell \qquad \{(19) \text{ and } A_6\}$	(20)
$\Rightarrow (\bigwedge_{i=1}^{m} \int \operatorname{Run}_{i} = \lceil \ell/T_i \rceil C_i)^{\frown} ((\int \bigvee_{i=1}^{m} \operatorname{Ru}_{i})^{\frown} (I_i)^{\frown} (I_i$	$\operatorname{Im}_i = \ell$	
$\wedge \bigwedge_{i=1}^{m} (\int \operatorname{Run}_{i} \leq \lfloor \ell / T_{i} \rfloor C_{i}) \wedge (\int \operatorname{Run}_{i}$	$k < \lfloor \ell / T_k \rfloor C_k)$	(21)
{(7), (13)	, (20), DC22, and DC23}	
$\Rightarrow (\bigwedge_{i=1}^{m} \int \operatorname{Run}_{i} = \lceil \ell/T_{i} \rceil C_{i})^{} (\sum_{i=1}^{m} C_{i}/T_{i})^{}$	> 1)	(22)
-	{(21) and Lemma 5}	
$\Rightarrow \sum_{i=1}^{m} C_i / T_i > 1$	{(22) }	(23)

	1.1 and 1.2 }	(24)
case 2: $\bigvee_{i=1}^{m} \beta(i)$ {case	split on (10)}	(25)
$\Rightarrow \ \Gamma \cup \Delta = \{1, \cdots, m\} \land \Delta \neq \emptyset,$		
where $\Gamma \widehat{=} \{1 \le i \le m \mid \alpha(i)\}$ and $\Delta \widehat{=} \{1 \le i \le m \mid \beta(i)\}.$	{(9) and (25)}	(26)
$\Rightarrow \bigwedge_{i \in \Delta} (\exists x_i \in \mathbb{R}. x_i \ge 0 \ mult_i \ ((\ell < T_i))$		
$\wedge (tt [Run_i] ((\int Run_i = 0) \land (\ell = x_i)))))$		(27)
{(2), (26), DC1	0 and DC20}	
$\Rightarrow mult_u \widehat{((\ell < T_u) \land (tt \widehat{Run}_u) \widehat{(\ell = x)}))$		
$\wedge (\bigwedge_{i \in \Delta} (mult_i \ ((\ell < T_i) \land (tt \ ((\int \operatorname{Run}_i = 0) \land (\ell = x)))),$		
where $x = \min\{x_i \mid i \in \Delta\}$ and $u = \min\{i \in \Delta \mid x_i = x\}$	{(27)}	(28)
$\Rightarrow \bigwedge_{i \in \Gamma} \alpha(i)$ {de	efinition of Γ}	(29)
$\Rightarrow \bigwedge_{i \in \Gamma} (\int \operatorname{Run}_i \leq \lfloor \ell / T_i \rfloor C_i)$	$\{A_4 \text{ and } (1)\}$	(30)
$\Rightarrow (tt^{}((\int \bigvee_{i=1}^{m} \operatorname{Run}_{i} = \ell) \land (\ell = x)))$		
$\vee (tt^{(()}(\sqrt{\sum_{i=1}^{m} \operatorname{Run}_{i} \neq \ell}) \land (\ell = x)))$	{tautology}	(31)
case 2.1 : $tt \cap ((\int \bigvee_{i=1}^{m} \operatorname{Run}_i \neq \ell) \land (\ell = x))$ {case	split on (31)}	(32)
$\Rightarrow tt^{((\lceil \bigwedge_{i=1}^{m} \neg \operatorname{Run}_{i}\rceil^{(\int \bigvee_{i=1}^{m} \operatorname{Run}_{i} = \ell))} \land (\ell = x)) \qquad \{(32)$	2) and DC20}	(33)
$\Rightarrow tt \left[\bigwedge_{i=1}^{m} \neg \mathrm{Std}_{i} \right] \left(\left(\int \bigvee_{i=1}^{m} \mathrm{Run}_{i} = \ell \right) \land (\ell < x) \right)$	$\{(33) \text{ and } A_3\}$	(34)
$\Rightarrow (\bigwedge_{i=1}^{m} \int \operatorname{Run}_{i} = \lceil \ell/T_{i} \rceil C_{i}) \cap ((\int \bigvee_{i=1}^{m} \operatorname{Run}_{i} = \ell) \land (\ell < x))$	$\{(34) \text{ and } A_6\}$	(35)
$\Rightarrow (\bigwedge_{i=1}^{m} \int \operatorname{Run}_{i} = \lceil \ell/T_{i} \rceil C_{i})^{} ((\int \bigvee_{i=1}^{m} \operatorname{Run}_{i} = \ell) \land (\bigwedge_{i \in \Delta} (\int \operatorname{Run}_{i} = \ell))$	$lun_i = 0))$	
$\wedge (\bigwedge_{i \in \Gamma} (\int \operatorname{Run}_i \leq \lfloor \ell/T_i \rfloor C_i)) \wedge (\int \operatorname{Run}_k < \lfloor \ell/T_k \rfloor \cdot C_k))$		(36)
{(7), (28), (30), DC2	2 and DC23}	
$\Rightarrow (\bigwedge_{i=1}^{m} \int \operatorname{Run}_{i} = \lceil \ell/T_{i} \rceil C_{i}) (\sum_{i=1}^{m} C_{i}/T_{i} > 1) $ ((36) an	nd Lemma 5}	(37)
$\Rightarrow \sum_{i=1}^{m} C_i / T_i > 1$	{(37)}	(38)
case 2.2: $tt^{((\int \bigvee_{i=1}^{m} \operatorname{Run}_{i} = \ell) \land (\ell = x))}$ {case	split on (31)}	(39)
C C	{(29) and (1)}	(40)
$\Rightarrow \bigwedge_{i \in \Gamma} \exists x_i \in \mathbb{R}. x_i \ge 0$		
$mult_{i}(\ell = x_{i}) \land (\int \operatorname{Run}_{i} = 0)) $ {(40)) and DC10}	(41)
$\Rightarrow (x_i < x) \lor (x_i \ge x)$	{tautology}	
		(43)
	1), (43), and	(44)
d	ef. of urgent}	
$\Rightarrow tt \left[\neg Std_i\right]^{(\ell = x)} $ {(28), (44)) and Sch_{EDF} }	(45)
$\Rightarrow \left(\int \operatorname{Run}_{i} = \left\lceil \ell / T_{i} \right\rceil C_{i} \right)^{-} (\ell = x)$	$\{(45) \text{ and } A_6\}$	(46)
	6) and DC22}	(47)
	5) and DC23}	(48)
	,	< - /

We have deduced $\sum_{i=1}^{m} C_i/T_i > 1$, a contradiction, hence completed the proof. \Box

6. Related Work

There is some other work on formal verification of scheduling theorems. Wilding [Wilding 1998] verified EDF using the Nqthm theorem prover and Dutertre [Dutertre 2000] verified priority ceiling protocol in PVS.

Recently, there is a lot of work applying techniques developed in model checking, mainly on timed automata [Alur and Dill 1994], to scheduling. Roughly, they can be classified into the schedulability analysis and the controller synthesis. The idea of former is to model real-time systems, including a particular scheduling policy, by (a variant of) timed automata. The schedulability problem is formulated as the reachability problem which can be model checked, see e.g. [Fersman *et al.* 2007]. The advantage of this approach is that it can handle more general scheduling problems (e.g., tasks are non-periodic) where the traditional schedulability analysis method has no general solutions. The controller synthesis approach is to achieve schedulability by construction. It was first proposed in [Wong-Toi and Hoffmann 1992] and further studied in [Maler *et al.* 1995,Altisen *et al.* 2002]. There is also considerable amount of research on optimal scheduling using timed automata, e.g. [Alur *et al.* 2001,Abdedaim *et al.* 2006,Bouyer *et al.* 2008].

Schedulability analysis based on other formal techniques has also been studied. For example, process algebra was used to model scheduling problems and schedulability is checked by symbolic weak bisimulation [Kwak *et al.* 1998].

However, it is unlikely that the model checking based methods for scheduling can be used to prove general scheduling theorems. Model checking is usually limited to a specific system, and is not easy to be extended to system with arbitrary number of tasks and parameters (execution times etc).

7. Conclusions

In this paper, we have formalised the two classic scheduling algorithms, i.e., RM and EDF, and formally proven their schedulability theorems. Our proofs are based in a large part on the intuitions of Liu and Layland's original work [Liu and Layland 1973]. This says that there are common grounds between formal and informal proofs. However, there is a lot of work to produce formal proofs from intuitive arguments. The reward for this somewhat arduous effort is that the proofs are now much more reliable. This does not mean that formal proofs are always correct, but there are certainly fewer chances for mistakes to creep in, because now concepts and definitions are formed without ambiguity and deduction is by well-established proof rules. Therefore, formal proofs can be subject to precise scrutiny. On the contrary, in an informal proof, concepts and definitions can be ambiguous, deduction can be not much more than hand waving, consequently, mistakes are more likely to occur, and one may remain unconvinced for something which is indeed correct. This has indeed happened with the informal proof of RM.

A proof is only meaningful if the assumptions are correct. In this paper in particular, the assumptions model the environment and the scheduling algorithms. These assumptions are based on the intuitive understanding of the system (at a lower level, one may want to formally verify whether these assumptions are indeed properties of the system, but this is out of the scope of the current paper). Most of the assumptions do not pose any questions, but there is an exception with A_6 . The current form stipulates that if a task is not requesting at the end of an interval, then the maximal required execution time over the whole interval has been satisfied. This is not a problem if there are no overflows happened before the last period is started. However, when there is an overflow happened before the last period, our assumption is based on the view that the missing execution time will be carried over to the subsequent periods. A particular system may be implemented in a different way, for example, the task which has not completed in a period is simply removed, or the system calls an exception handling procedure when an overflow occurs. Ideally, the formal model should include all these cases, but we have not been able to do so. We can of course formalise different models and prove the feasibility conditions separately. In fact, some of the earlier work assumed that incomplete tasks are removed. Most of the proof steps are actually similar.

In this paper, the formal logic we used is DC. DC is designed to specify and reason about real time behavior over intervals, and is a suitable tool for formalising scheduling theories because the accumulated running time of a task is associated with an interval and can be conveniently expressed. DC provides an abstraction for intervals (so one does not refer to an interval explicitly in a formula, say in the form of [b,e]). The price for this is that the logic is more demanding to learn. However, many computer professionals may not have a strong background in logic. For people who are more accustomed to set theory or classic first order logic, an alternative is to use basically the semantics of DC and this gives a first order logic with a special variable for time. A calculus similar to this, but in a set-theoretic notation, is the Timed Interval Calculus [Fidge *et al.* 1998]. Another shortcoming of DC is that to follow the principle "small is beautiful", state variables are restricted to a special kind (namely, boolean functions of time) and terms are only defined over intervals. These restrictions are not a serious problem for our paper, except the scheduling policy of EDF has to be expressed in a somewhat indirect way. One would like to be able to talk more directly about it, say by having a function which gives the next deadline value. It is possible to extend DC to include such features and in fact several variants of DC have been developed, e.g. Extended Duration Calculus [Zhou *et al.* 1993]. However, having several variants of DC may not be desirable. In this case, one may also consider using the first order logic over time corresponding to the semantics of DC, since less work is expected in extending it.

The proofs in this paper are the longest on applications of DC as far as we are aware of. We found it is difficult to be rigorous with previous styles of DC proofs in the literature to handle proofs of this size. Our way of writing DC proofs is new and we expect it to be useful in writing other long proofs in DC.

A great deal of research has been done on the theory and implementation of theorem proving systems, providing automatic or semi-automatic support to various formal logics. Proofs conducted on a theorem prover are usually much more reliable than those by human beings, because the system is carefully constructed by specialists and constantly debugged by the large number of people using it. A couple of theorem provers exist for DC, usually based on some other theorem provers for DC. When the theorem provers for DC are further developed, it may be interesting to try the proofs in this paper mechanically.

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Appendix A.

We now prove Lemma 4. As in Liu and Layland's proof, we first consider the case that one period is at least half of any other period, or formally, $0 < T_i/T_i < 2$ for all $1 \leq i, j \leq m$.

In this case, $non_{inc}(C, T)$ holds if the inequality holds for every period points.

LEMMA 6. If
$$0 < T_i/T_j < 2$$
 for all $1 \le i, j \le m$, then
 $non_inc(C,T) \Leftrightarrow \bigwedge_{i=1}^m (T_i \le \sum_{j=1}^m [T_i/T_j]C_j).$

PROOF. By the definition of $non_inc(C, T)$ (full utilisation), the \Rightarrow direction is trivial, since it just corresponds to the special cases where x is instantiated by the periods respectively. We next prove the \Leftarrow direction. For notational convenience, let $T_0 = 0$.

$$(0 < x \le T_m) \land (\bigwedge_{i=1}^m (\sum_{j=1}^m [T_i/T_j]C_j \ge T_i))$$

$$(1)$$

$$\Rightarrow (\bigvee_{i=1}^{m} (T_{i-1} < x \le T_i)) \land (\bigwedge_{i=1}^{m} (\sum_{j=1}^{m} [T_i/T_j] C_j \ge T_i))$$
(2)

$$\Rightarrow \bigvee_{i=1}^{m} \left(\left(T_{i-1} < x \le T_i \right) \land \left(\bigwedge_{i=1}^{m} \left(\sum_{j=1}^{m} \left[T_i / T_j \right] C_j \ge T_i \right) \right) \right)$$
(3)

$$\Rightarrow \bigvee_{i=1}^{m} \left(\left(x \le T_i \right) \land \left(\bigwedge_{j=1}^{m} \left[\left\lceil x/T_j \right\rceil = \left\lceil T_i/T_j \right\rceil \right) \right) \land \left(\sum_{i=1}^{m} \left\lceil T_i/T_j \right\rceil C_j \ge T_i \right) \right)$$
(4)

$$\{0 < T_i/T_j < 2 \text{ for all } 1 \le i, j \le m \}$$

$$\Rightarrow \bigvee_{i=1}^{m} (\sum_{j=1}^{m} \lceil x/T_j \rceil C_j \ge x)$$
(5)

$$\Rightarrow \sum_{j=1}^{m} \lceil x/T_j \rceil C_j \ge x \tag{6}$$

The next lemma indicates that the minimal value is reached when $C_i = T_{i+1} - T_i$ for i = 1, ..., m - 1 and $C_m = 2T_1 - T_m$.

LEMMA 7. If $0 < T_i/T_j < 2$ for all $1 \le i, j \le m$, then $\min\{\sum_{i=1}^m C_i/T_i \mid non_inc(C, T)\}$ $= \min\{\sum_{i=1}^m C_i/T_i \mid (\bigwedge_{i=1}^{m-1} C_i = T_{i+1} - T_i) \land C_m = 2T_1 - T_m\}.$

PROOF. By definition, it is easy to prove *non_inc*(*C*, *T*) holds when $C_i = T_{i+1} - T_i$ for $i = 1 \cdots m - 1$ and $C_m = 2T_1 - T_m$ and therefore follows that

$$\min\{\sum_{i=1}^{m} C_i/T_i \mid non_inc(C, T)\} \\ \leq \min\{\sum_{i=1}^{m} C_i/T_i \mid \bigwedge_{i=1}^{m-1} C_i = T_{i+1} - T_i \land C_m = 2T_1 - T_m\}$$

We next prove the converse direction. For this, it is enough to prove that if $non_{inc}(C, T)$ holds, then $\sum_{i=1}^{m} C_i/T_i \ge (\sum_{i=1}^{m-1} (T_{i+1} - T_i)/T_i) + (2T_1 - T_m)/T_m$. From Lemma 6, it results that there exist $\alpha_i \ge 1, i = 1 \dots m$ such that

$$C_{1} + C_{2} + \cdots + C_{m-1} + C_{m} = \alpha_{1}T_{1}$$

$$2C_{1} + C_{2} + \cdots + C_{m-1} + C_{m} = \alpha_{2}T_{2}$$

$$\vdots$$

$$2C_{1} + 2C_{2} + \cdots + 2C_{m-1} + C_{m} = \alpha_{m}T_{m}$$

Thus,

$$C_1 = \alpha_2 T_2 - \alpha_1 T_1$$

$$\vdots$$

$$C_{m-1} = \alpha_m T_m - \alpha_{m-1} T_{m-1}$$

$$C_m = 2\alpha_1 T_1 - \alpha_m T_m$$

Hence,

Now we are ready to calculate the minimal value. The calculation in Liu and Layland's paper [Liu and Layland 1973] is complicated and missing steps. In the following, a straightforward proof using only elementary mathematics is given.

Lemma 8. If $0 < T_i/T_j < 2$ for all $1 \le i, j \le m$, then $\min\{\sum_{i=1}^m C_i/T_i \mid (\bigwedge_{i=1}^{m-1} (C_i = T_{i+1} - T_i)) \land C_m = 2T_1 - T_m\} = m(2^{\frac{1}{m}} - 1).$

PROOF. For $i = 1 \dots m - 1$, $C_i/T_i = T_{i+1}/T_i - 1$, and $C_m/T_m = 2T_1/T_m - 1$. It follows that $\sum_{i=1}^m C_i/T_i = (\sum_{i=1}^{m-1} T_{i+1}/T_i) + 2T_1/T_m - m$. By a simple mathematical property, the minimal value of $((\sum_{i=1}^{m-1} T_{i+1}/T_i) + 2T_1/T_m)/m$ is equal to $((T_2/T_1)(T_3/T_2) \cdots (T_m/T_{m-1})(2T_1/T_m))^{\frac{1}{m}} = 2^{\frac{1}{m}}$. Therefore, the minimal value of $\sum_{i=1}^m C_i/T_i = m(2^{\frac{1}{m}} - 1)$. \Box

This indicates Lemma 4 is true under the assumption that any period is at least half of any other period. What remains to be shown is that the lemma is still true without the assumption. Let $q_i = \lfloor T_m/T_i \rfloor$ and $T'_i = q_i T_i$ for $1 \le i \le m$. According to this definition, it is easy to show the following.

LEMMA 9. (1) $q_i \ge 1$ for any $1 \le i \le m$.

- (2) $\lceil T_m/T_i \rceil \le q_i + 1$ for any $1 \le i \le m$.
- (3) $0 < T'_i/T'_i < 2$ for any $1 \le i, j \le m$.

PROOF. Obvious and omitted. \Box

LEMMA 10. Let $q_i = \lfloor T_m/T_i \rfloor$, $T'_i = q_i T_i$ for $1 \le i \le m$, and $C'_i = C_i$ for i = 1, ..., m-1, $C'_m = C_m + \sum_{i=1}^{m-1} (q_i - 1)C_i$. If $non_inc(C, T)$, then $non_inc(C', T')$.

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PROOF. We prove the lemma by contradiction.

$$\neg non_inc(C', T')$$

$$\Rightarrow \bigvee_{i=1}^{m} (\sum_{j=1}^{m} \lceil T'_i / T'_j \rceil C'_j < T'_i)$$

$$\Rightarrow \bigvee_{i=1}^{m} (\sum_{T'_j < T'_i} 2C'_j + \sum_{T'_j \ge T'_i} C'_j < T'_i)$$

$$\{ \text{for any } j \text{ such that } T'_j < T'_i, \lceil T'_i / T'_j \rceil = 2,$$

$$\text{for any } j \text{ such that } T'_j \ge T'_i, \lceil T'_i / T'_j \rceil = 1 \}$$

$$\Rightarrow \bigvee_{i=1}^{m} (\sum_{T'_j < T'_i} (q_j + 1)C_j + \sum_{T'_j \ge T'_i} q_jC_j < T'_i)$$

$$\{ \text{definition of } C'_m \}$$

$$\Rightarrow \bigvee_{i=1}^{m} (\sum_{j=1}^{m} \lceil T'_i / T_j \rceil C_j < T'_i)$$

$$\{ \text{Lemma } 9 \}$$

This is in contradiction to *non_inc*(C, T), and completes the proof. \Box

LEMMA 11.
$$\min\{\sum_{i=1}^{m} C_i/T_i \mid non_inc(C, T) \land 0 < T_i/T_j < 2 \text{ for all } 1 \le i, j \le m\}$$

= $\min\{\sum_{i=1}^{m} C_i/T_i \mid non_inc(C, T)\}.$

PROOF. Let

$$S = \{\sum_{i=1}^{m} C_i/T_i \mid non_inc(C,T)\},\$$

$$S' = \{\sum_{i=1}^{m} C_i/T_i \mid non_inc(C,T) \land 0 < T_i/T_j < 2 \text{ for each } 1 \le i, j \le m\}.$$

Assume $U = \sum_{i=1}^{m} C_i/T_i \in S$ and $non_inc(C, T)$. Let $q_i = \lfloor T_m/T_i \rfloor$, $T'_i = q_iT_i$, $C'_i = C_i$ $(i = 1, \dots, m-1)$, $T'_m = T_m$, $C'_m = C_m + \sum_{i=1}^{m-1} (q_i - 1)C_i$. It follows from Lemma 9 that $0 < T'_i/T'_j < 2$ and from Lemma 10 that $non_inc(C', T')$. It is easy to prove

$$U' = \sum_{i=1}^{m} C'_i / T'_i = U + \sum_{i=1}^{m-1} C_i (q_i - 1)(1/T_m - 1/T'_i) \le U.$$

Therefore, min $S' \leq \min S$. On the other hand, it is easy to see min $S' \geq \min S$ since $S' \subseteq S$. Thus, min $S' = \min S$. \Box

Finally, Lemma 4 follows from Lemma 8 and Lemma 11.

In Liu and Layland's original proof for what we formalise as Lemma 7, they proposed two transformations. The transformations are not used in our proof of Lemma 7, since we have found a simpler proof. However, the transformation may be of interests for other reasons. The first transformation can be expressed by the following lemma

LEMMA 12. Assume $0 < T_i/T_j < 2$ for all $1 \le i, j \le m, C_1 = T_2 - T_1 + \Delta$, $\Delta > 0, C'_1 = T_2 - T_1, C'_2 = C_2 + \Delta, C'_i = C_i (i = 3, \dots, m)$, If non_inc(C, T), then non_inc(C', T).

Proof.

$$\begin{split} \sum_{i=1}^{m} [T_{1}/T_{i}]C_{i}' &= \sum_{i=1}^{m} C_{i}' = \sum_{i=1}^{m} C_{i} \geq T_{1} \\ \sum_{i=1}^{m} [T_{2}/T_{i}]C_{i}' &= \sum_{i=1}^{m} C_{i}' + C_{1}' \geq T_{1} + (T_{2} - T_{1}) = T_{2} \\ &\vdots \\ \sum_{i=1}^{m} [T_{m}/T_{i}]C_{i}' &= \sum_{i=1}^{m} [T_{m}/T_{i}]C_{i} \geq T_{m} \\ non_{inc}(C', T) & \{lemma 6\} \end{split}$$

In the second transformation, Liu and Layland made a mistake. This was reported in [Dong *et al.* 1999,Devillers and Goossens 2000]. In [Dong *et al.* 1999], we gave the following corrected version

LEMMA 13. Assume $0 < T_i/T_j < 2$ for all $1 \le i, j \le m, C_1 = T_2 - T_1 - \Delta$, $\Delta > 0, C'_1 = T_2 - T_1, C'_i = C_i(i = 2 \cdots m), C'_m = C_m - 2\Delta^{3}$ If non_inc(C, T), then non_inc(C', T).

PROOF.

$$\begin{split} \sum_{i=1}^{m} [T_1/T_i] C'_i &= \sum_{i=1}^{m} [T_2/T_i] C_i - C'_1 \ge T_2 - (T_2 - T_1) = T_1 \\ \sum_{i=1}^{m} [T_2/T_i] C'_i &= \sum_{i=1}^{m} [T_2/T_i] C_i \ge T_2 \\ &\vdots \\ \sum_{i=1}^{m} [T_m/T_i] C'_i &= \sum_{i=1}^{m} [T_m/T_i] C_i \ge T_m \\ non_{inc}(C', T) & \{Lemma \, 6\} \end{split}$$

This transformation only makes sense when $C_m \ge 2\Delta$ and therefore cannot be applied in all cases. However, it is possible to prove Lemma 7 along the line as follows. First, we can extend Lemma 12 to all $i \le m - 1$ (consider Lemma 12 in the case i = 1), and by applying it repeatedly, we obtain $C_i \le T_{i+1} - T_i$ for all i = 1, ..., m - 1. Next, we can apply a new transformation indicated by the following lemma.

LEMMA 14. Assume $0 < T_i/T_j < 2$ for all $1 \le i, j \le m, C_i = T_{i+1} - T_i - \Delta_i, \Delta_i \ge 0, C'_i = T_{i+1} - T_i, i = 1 \dots m - 1, C'_m = C_m - 2(\Delta_1 + \dots + \Delta_{m-1})$. If non_inc(C, T), then $C'_m \ge 0$ and non_inc(C', T).

Proof.

$$2C_{1} + 2C_{2} + \dots + 2C_{m-1} + C_{m} \ge T_{m} \qquad \{non_inc(C, T)\} \\ \Rightarrow 2(C'_{1} - \Delta_{1}) + 2(C'_{2} - \Delta_{2}) + \dots + 2(C'_{m-1} - \Delta_{m-1}) + C_{m} \ge T_{m} \\ \Rightarrow 2(C'_{1} + C'_{2} + \dots + C'_{m-1}) - 2(\Delta_{1} + \Delta_{2} + \dots + \Delta_{m-1}) + C_{m} \ge T_{m} \\ \Rightarrow 2(T_{m} - T_{1}) - 2(\Delta_{1} + \Delta_{2} + \dots + \Delta_{m-1}) + C_{m} \ge T_{m} \\ \Rightarrow C_{m} - 2(\Delta_{1} + \Delta_{2} + \dots + \Delta_{m-1}) \ge 2T_{1} - T_{m} \\ \Rightarrow C'_{m} \ge 2T_{1} - T_{m} \\ \Rightarrow C'_{m} \ge 0$$

and

$$C'_{1} + C'_{2} + \dots + C'_{m-1} + C'_{m} \geq T_{m} - T_{1} + 2T_{1} - T_{m} = T_{1}$$

$$\vdots$$

$$2C'_{1} + 2C'_{2} + \dots + 2C'_{j-1} + C'_{j} + \dots + C'_{m} \geq T_{m} - T_{1} + T_{j} - T_{1} + 2T_{1} - T_{m} = T_{j}$$

$$\vdots$$

$$2C'_{1} + 2C'_{2} + \dots + 2C'_{m-1} + C'_{m} \geq 2(T_{m} - T_{1}) + 2T_{1} - T_{m} = T_{m}$$

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³ In Liu and Layland's paper, they let $C'_2 = C_2 - 2\Delta$ and $C'_m = C_m$. A counterexample was given in [Devillers and Goossens 2000]

It is easy to prove that these transformations will not increase the utilisation factor, and from the proof of Lemma 13 that $C'_m \ge 2T_1 - T_m$, hence, Lemma 7 follows.