Model Checking Markov Chains

Lecture 2: PCTL Counterexamples

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Lecture at Model Checking Summerschool, October 11, 2010





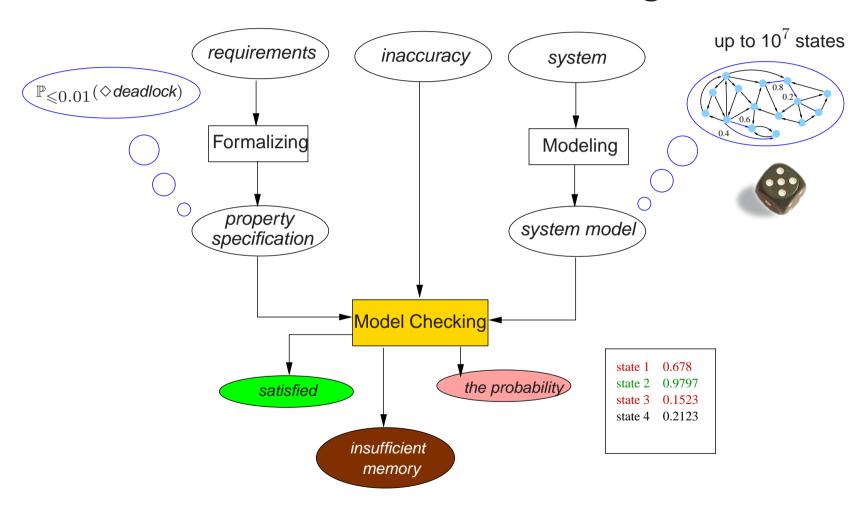
Content of this lecture

- ⇒ What is a counterexample?
 - motivation, definition, properties
 - Counterexample generation
 - algorithms, time complexity, examples
 - Representing counterexamples
 - weighted regular expressions, optimisations





Probabilistic model checking







- Are of utmost importance:
 - diagnostic feedback, key to abstraction-refinement, schedule synthesis . . .
 - fit to paradigm "model checking = bug hunting"





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 - $\Diamond \Phi$: a $\neg \Phi$ -path leading to a $\neg \Phi$ cycle
 - BFS yields shortest counterexamples





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- CTL counterexamples are (mostly) finite trees
 - universal CTL\LTL: trees or proof-like counterexample
 - existential CTL: witnesses, annotated counterexample



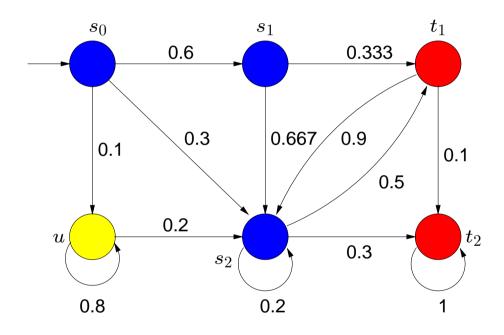


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- This talk: PCTL counterexamples for DTMCs





Discrete-time Markov Chain



a DTMC is a triple (S,\mathbf{P},L) with state space S and state-labelling L and \mathbf{P} a stochastic matrix with $\mathbf{P}(s,s')=$ one-step probability to jump from s to s'





Probabilistic CTL (Hansson & Jonsson, 1994)

• For $a \in AP$, $J \subseteq [0,1]$ an interval with rational bounds, and $h \in \mathbb{N}$:

$$\Phi ::= a \mid \Phi \wedge \Phi \mid \neg \Phi \mid \mathbb{P}_{J}(\varphi)$$

$$\varphi ::= \Phi \cup \Phi \mid \Phi \cup^{\leqslant h} \Phi$$

- $s_0 s_1 s_2 \dots \models \Phi \cup^{\leqslant h} \Psi$ if Φ holds until Ψ holds within h steps
- $s \models \mathbb{P}_{J}(\varphi)$ if probability of set of φ -paths starting in s lies in J

abbreviate $\mathbb{P}_{[0,0.5]}(\varphi)$ by $\mathbb{P}_{\leqslant 0.5}(\varphi)$ and $\mathbb{P}_{]0,1]}(\varphi)$ by $\mathbb{P}_{>0}(\varphi)$ and so on





Topics of this lecture

- What is a PCTL counterexample?
 - a set of paths with sufficient probability mass
- How to determine smallest counterexamples?
 - exploit k-shortest path algorithms
- How about the size of counterexamples?
 - well, they may be excessively large and incomprehensible
- Can we do better?
 - yes, represent counterexamples by regular expressions!
- How to obtain (short) regular expressions?
 - use automata theory and some heuristics





PCTL counterexamples for $s \not\models \mathbb{P}_{\leq p}(\varphi)$

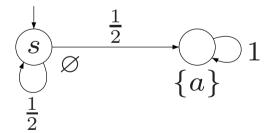
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 - $\sigma \in C$ implies σ starts in s and $\sigma \models \varphi$
 - $\Pr(C) = \sum_{\sigma \in C} \mathbf{P}(\sigma)$ exceeds p





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- Property: counterexamples for non-strict bounds $\leq p$ are *finite*



A DTMC with infinite counterexample for $s \not\models \mathbb{P}_{<1}(\lozenge a)$





PCTL counterexamples for $s \not\models \mathbb{P}_{\leq p}(\varphi)$

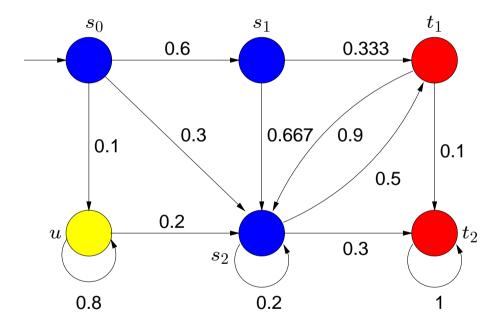
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- Property: counterexamples for non-strict bounds $\leq p$ are *finite*
- C is *minimal* if $|C| \leqslant |C'|$ for any counterexample C'
- *C* is *smallest* if:

C is minimal, and $\Pr(C)\geqslant\Pr(C')$ for any minimal counterexample C'





Evidences for $s_0 \not\models \mathbb{P}_{\leqslant \frac{1}{2}}(\boldsymbol{a} \cup \boldsymbol{b})$

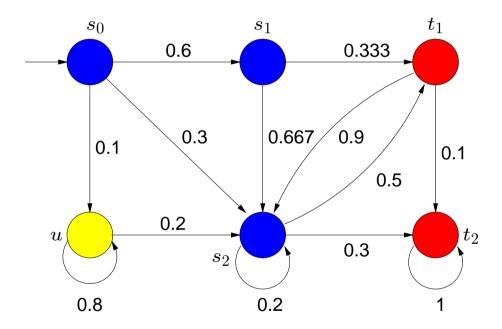


evidences	prob.
$\sigma_1 = s_0 s_1 t_1$	0.2
$\sigma_2=s_0s_1s_2t_1$	0.2
$\sigma_3 = s_0s_2t_1$	0.15
$\sigma_4=s_0s_1s_2t_2$	0.12
$\sigma_5=s_0s_2t_2$	0.09
•••	





Strongest evidences (SEs)

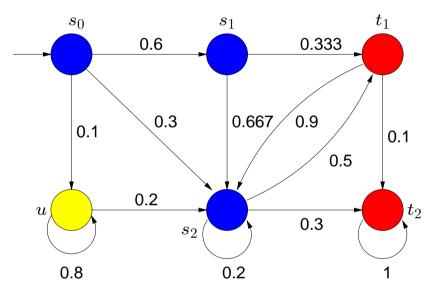


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Counterexamples for $s_0 \not\models \mathbb{P}_{\leqslant \frac{1}{2}}(\boldsymbol{a} \cup \boldsymbol{b})$



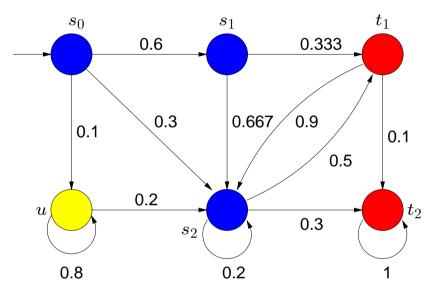
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counterexample	card.	prob.
$\set{\sigma_1,\ldots,\sigma_5}$	5	0.76
$\set{\sigma_1 \text{ or } \sigma_2, \ldots, \sigma_5}$	4	0.56
$\set{\sigma_1,\sigma_2,\sigma_4}$	3	0.52
$\set{\sigma_1,\sigma_2,\sigma_3}$	3	0.55





Counterexamples for $s_0 \not\models \mathbb{P}_{\leqslant \frac{1}{2}}(\boldsymbol{a} \cup \boldsymbol{b})$



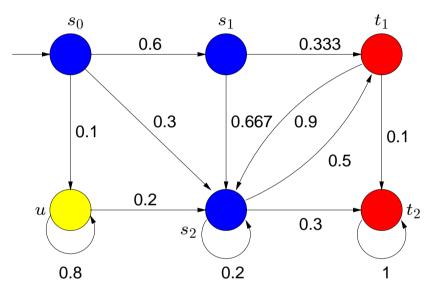
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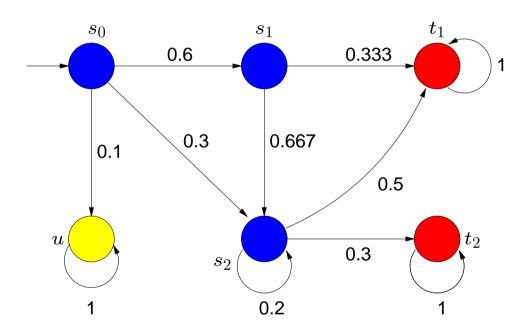
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Obtaining smallest counterexamples

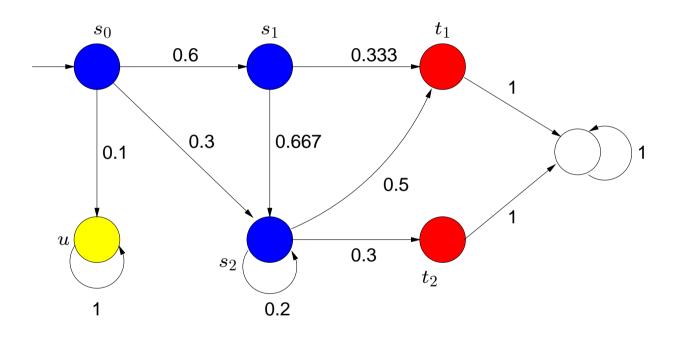


Step 1: make all Ψ -states and all $\neg \Phi \land \neg \Psi$ -states absorbing





Adapting a bit more

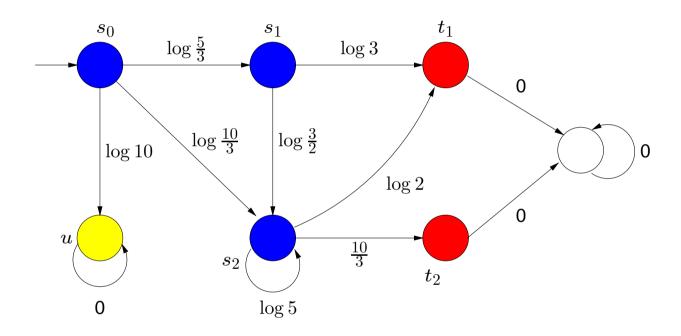


Step 2: insert a sink state and redirect all outgoing edges of Ψ -states to it





A weighted digraph



Step 3: turn it into a weighted digraph with $w(s,s') = \log\left(\frac{1}{\mathbf{P}(s,s')}\right)$





A simple derivation

For finite path $\sigma = s_0 s_1 s_2 \dots s_n$:

$$w(\sigma) = w(s_0, s_1) + w(s_1, s_2) + \dots + w(s_{n-1}, s_n)$$

$$= \log \frac{1}{\mathbf{P}(s_0, s_1)} + \log \frac{1}{\mathbf{P}(s_1, s_2)} + \dots + \log \frac{1}{\mathbf{P}(s_{n-1}, s_n)}$$

$$= \log \frac{1}{\mathbf{P}(s_0, s_1) \cdot \mathbf{P}(s_1, s_2) \cdot \dots \cdot \mathbf{P}(s_{n-1}, s_n)}$$

$$= \log \frac{1}{\mathbf{P}(\sigma)}$$

$$\underbrace{\Pr(\widehat{\sigma}) \geqslant \Pr(\sigma)}_{\text{in DTMC }\mathcal{D}} \quad \text{if and only if} \quad \underbrace{w(\widehat{\sigma}) \leqslant w(\sigma)}_{\text{in digraph }G(\mathcal{D})}$$





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What does this mean?

- Finding a strongest evidence is a shortest path (SP) problem
 - apply standard SP algorithms, or Viterbi's algorithm ⇒ linear time complexity





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 - dynamically determine k: generate C incrementally and halt when Pr(C) > p





What does this mean?

- Finding a strongest evidence is a shortest path (SP) problem
 - apply standard SP algorithms, or Viterbi's algorithm ⇒ linear time complexity
- Finding a shortest counterex is a k-shortest path (KSP) problem
 - dynamically determine k: generate C incrementally and halt when Pr(C) > p
- This also applies to $\mathbb{P}_{\geqslant p}(\varphi)$ properties, as

$$\begin{array}{ll} \mathbb{P}_{\geqslant p}(\mathbf{\Phi}\,\mathsf{U}\,\Psi) & \equiv & \mathbb{P}_{\leqslant 1-p}(\underbrace{(\mathbf{\Phi}\,\wedge\,\neg\Psi)}_{\Phi^*}\,\mathsf{W}\,\underbrace{(\neg\Phi\,\wedge\,\neg\Psi)}_{\Psi^*})\\ \\ & \equiv & \mathbb{P}_{\leqslant 1-p}(\Phi^*\,\mathsf{U}\,(\Psi^*\,\vee\,\textit{at}_{\mathsf{bscc}(\Phi^*)})) \end{array}$$





Time complexity

counterexample problem	shortest path problem	algorithm	time complexity
unbounded SE	SP	Dijkstra	$\mathcal{O}(M + N \cdot \log N)$
bounded h SE	HSP	Bellman-Ford / Viterbi	$\mathcal{O}(h\!\cdot\! M)$
unbounded SC	KSP	Eppstein	$\mathcal{O}(M + N \cdot \log N + k)$
bounded h SC	HKSP	adapted REA	$\mathcal{O}\left(h \cdot M + h \cdot k \cdot \log N\right)$

N = |S|, M = # transitions, h = hop count, k = # shortest paths

including costs yields an instance of the NP-complete RSP problem





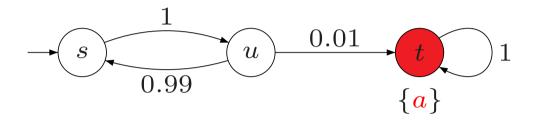
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On the size of counterexamples



A smallest counterexample for $s \not\models \mathbb{P}_{\leq 0.9999}(\diamondsuit a)$ contains paths

$$sut, susut, sususut, \ldots, \underbrace{su}_{k \text{ times}} t$$

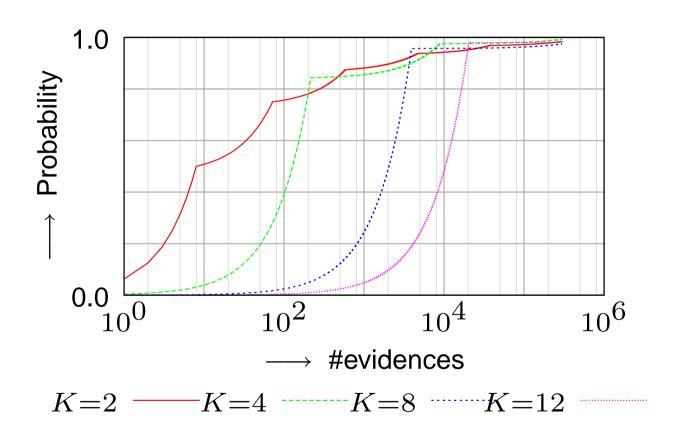
where k is the smallest integer such that $1-0.99^{k-1} > 0.9999$

The smallest counterexample has k=689 evidences





Synchronous leader election $\mathbb{P}_{\leq 0.99}(\lozenge leader)$



size of counterexample is double exponential in problem size (see paper)





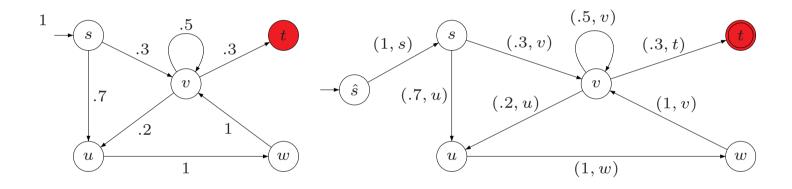
Use regular expressions!

- Size of counterexamples is mainly influenced by loops
 - each loop-traversal yields another path in counterexample
- Idea: represent sets of "similar" finite paths by a regular expression
- How?
 - DTMC (rooted at s) \longrightarrow DFA
 - DFA \longrightarrow most probable paths \longrightarrow regular expression r
- Such that:
 - probability of regular expression r exceeds p (= r is a counterexample)
 - r is "minimal": deletion of some "branch" of r yields no counterexample





From DTMCs to DFAs



alphabet Σ consist of symbols of the form (p, s)





From DTMCs to DFA

For DTMC $\mathcal{D}=(S,\mathbf{P},L)$, state s, and property $\mathbb{P}(\diamondsuit^{\leqslant h}\mathbf{t})$, DFA $\mathcal{A}_{\mathcal{D}}=(S',\Sigma,\tilde{\mathbf{s}},\delta,\mathbf{t})$

	DTMC	DFA	
state space	S	$S \cup \{\tilde{\boldsymbol{s}}\}$	
initial state	s	$\tilde{s} \notin S$	
goal/accepting state	t	t	
alphabet	_	$\Sigma \subset \boxed{[0,1] imes S}$	
transitions	$s_1 \xrightarrow{p} s_2$	$s_1 \xrightarrow{(p, s_2)} s_2$	
	_	$ ilde{oldsymbol{s}} \stackrel{(1,s)}{\longrightarrow} s$	





Regular expressions [Daws'04]

The set of regular expressions $\mathcal{R}(\Sigma)$:

$$r,r'::=arepsilon \qquad empty \ | \ (p,s) \quad ext{letter} \ | \ r|r' \quad ext{choice} \ | \ r.r' \quad ext{catenation} \ | \ r^* \quad ext{repetition}$$





Regular expressions [Daws'04]

The set of regular expressions $\mathcal{R}(\Sigma)$:

Evaluation $val: \mathcal{R}(\Sigma) \to \mathbb{R}_{\geqslant 0}$:

$$\begin{array}{lll} val(\varepsilon) & = & 1 \\ val((p,s)) & = & p \\ val(r|r') & = & val(r) + val(r') \\ val(r.r') & = & val(r) \cdot val(r') \\ val(r^*) & = & \begin{cases} 1 & \text{if } val(r) = 1 \\ \frac{1}{1-val(r)} & \text{otherwise} \end{cases} \end{array}$$





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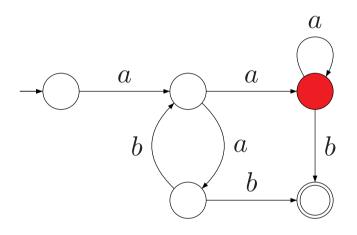
For regular expression r of DFA $\mathcal{A}_{\mathcal{D}}$ with accept state t:

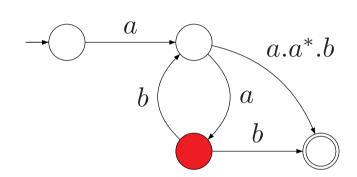
$$val(r) = \Pr^{\mathcal{D}} \{ \sigma \in \mathit{Paths}(s) \mid \sigma \models \Diamond t \}$$

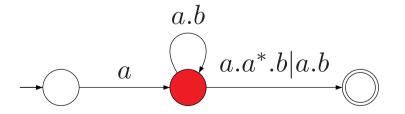




State elimination [Brzozowski & McCluskey jr., 1962]





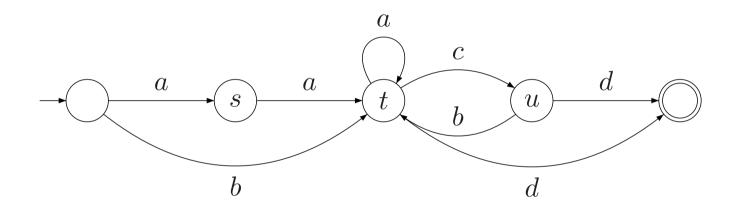


$$-\underbrace{a.(a.b)^*.(a.a^*.b|a.b)}_{}$$





Ordering matters



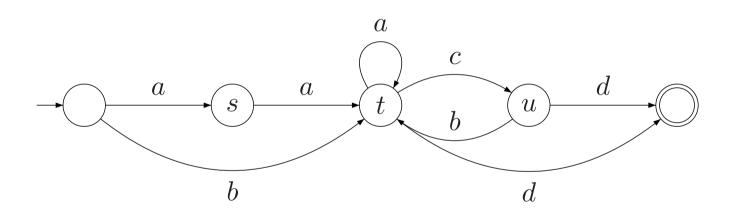
Ordering s < u < t yields $(aa|b)(a|cb)^*(cd|d)$

Ordering s < t < u yields $(aa|b)a^*c(ba^*c)^*(ba^*d|d)|(aa|b)a^*d$





Ordering matters



Finding the optimal removal ordering takes time $\mathcal{O}(N!)$ where |S|=N

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Heuristic [Han & Wood'07]

"eliminate all non-bridge states before bridge states"

- 1. Find all *bridge* states q_1 through q_{n-1}
 - the path of every word $w \in \mathcal{L}(\mathcal{A})$ goes through q_i
 - ullet once this path visits q_i it will not visit states visited prior to q_i
- 2. Perform vertical chopping
 - $\mathcal{A} = \mathcal{A}_1 \cdot \mathcal{A}_2 \cdot \ldots \cdot \mathcal{A}_n$ where \mathcal{A}_i is "connected" to \mathcal{A}_i via bridge q_i
- 3. For each A_i perform *horizontal chopping*
 - $\bullet \ \mathcal{A}_i = \mathcal{A}_{i,1} | \mathcal{A}_{i,2} | \dots | \mathcal{A}_{i,k}$
- 4. For each automaton A_i , j goto step 1.





Time complexity

"eliminate all non-bridge states before bridge states"

1. Find all *bridge* states q_1 through q_{n-1}

in linear time

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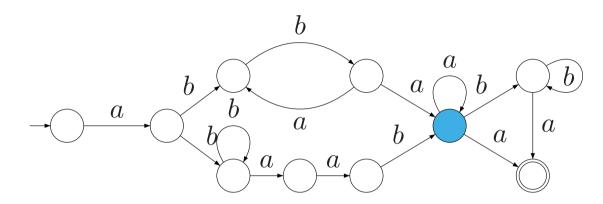
in linear time

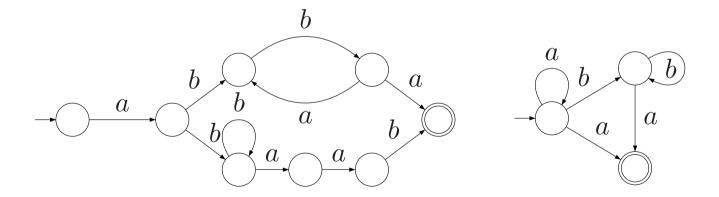
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Vertical chopping

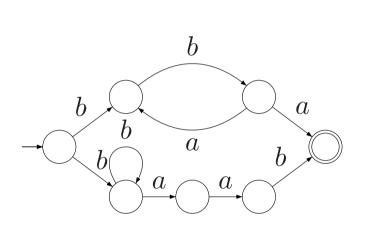


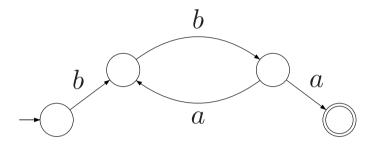


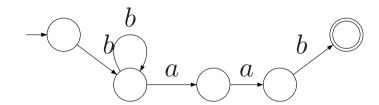




Horizontal chopping











Maximal union subexpressions

 r_1 is a maximal union subexpression (MUS) of regular expression r if:

$$r = r_1 \mid r_2$$
 modulo the congruence $(\mathbf{R_1})$ - $(\mathbf{R_3})$

where for some $r_2 \in \mathcal{R}(\Sigma)$:

$$(\mathbf{R_1}) \qquad \qquad r \equiv r \mid \varepsilon$$

$$(\mathbf{R_2}) \qquad \qquad r_1 \mid r_2 \equiv r_2 \mid r_1$$

$$(\mathbf{R_3}) \qquad \qquad r_1 \mid (r_2 \mid r_3) \equiv (r_1 \mid r_2) \mid r_3$$

a MUS can be regarded as a main path from the initial state to a accept state





Algorithm for regular expressions

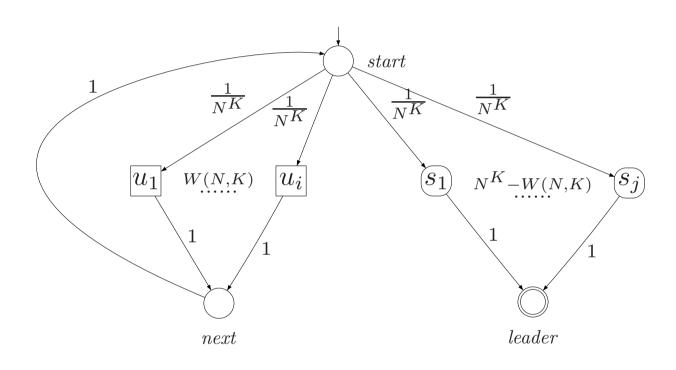
```
Require: DFA \mathcal{A}_{\mathcal{D}} = (S, \Sigma, s, \delta, \{t\}), and p \in [0, 1]
Ensure: regular expression r \in \mathcal{R}(\Sigma) with val(r) > p
   \mathcal{A} := \mathcal{A}_{\mathcal{D}}, \ pr := 0; \ \text{priority queue} \ pq := \emptyset; \ k := 1;
   while pr \leqslant p do
      \sigma := the strongest evidence in \mathcal{A};
      forall s' \in \sigma \setminus \{s, \hat{s}, t\} do pq.enqueue(s'); end;
      while pq \neq \emptyset do
         \mathcal{A} := \text{eliminate}(pq.\text{dequeue}()); \quad r_k := \text{the created MUS};
         pr := pr + val(r_k); \quad \mathcal{A} := \mathsf{eliminate}(r_k);
         if (pr > p) then break else k := k + 1;
      endwhile;
   endwhile:
   return r_1 \mid \ldots \mid r_k.
```

this approach works for strict and non-strict bounds





Leader election revisited



Regular expression for the counterexample:

$$r(N,K) = start. [(u_1|\cdots|u_i).next. start]^*. (s_1|\cdots|s_j). leader$$

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Model reduction

The size of a counterexample is determined by

- traversing the same loop for different times
 - ⇒ using Kleene stars in regular expressions

- large number of states
 - → model reduction
 - 1. bisimulation minimization
 - 2. SCC minimization

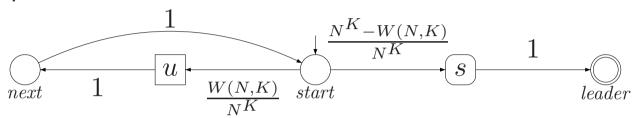
Model reduction is done prior to counterexample generation





Leader election re-revisited

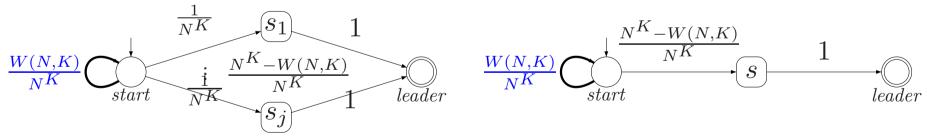
Bisimulation quotient:



$$r_{\sim}(N,K) = start. (u.next.start)^*.s. leader$$

After aggregating SCCs:

SCC aggregation of bisimulation quotient:



$$r^{scc}(N,K) = start.start^*.(s_1|\cdots|s_j).leader \qquad r^{scc}_{\sim}(N,K) = start.start^*.s.leader$$





Other approaches

Heuristic search algorithms for CTMCs

(Aljazzar et al. FORMATS 2005, 2006)

Counterexamples for CTMCs

(Han & Katoen ATVA 2007)

Counterexamples for conditional PCTL

(Andres & van Rossum TACAS 2008)

Proof refutations for probabilistic programs

(McIver et al. FM 2008)

Counterexample-guided abstraction refinement

(Hermanns et al. CAV 2008)

Counterexamples for MDPs

(Andres et al., HVC 2008, Aljazzar & Leue TR 2007)

Bounded MC for DTMC counterexamples

(Becker et al. VMCAI 2009)





Epilogue

- What is a PCTL (or quantitative LTL) counterexample?
 - a set of paths with sufficient probability mass
- How to determine smallest counterexamples?
 - exploit k-shortest path algorithms
- How about the size of counterexamples?
 - well, they may be excessively large and incomprehensible
- Can we do better?
 - yes, represent counterexamples by regular expressions!
- How to obtain (short) regular expressions?
 - use automata theory and some heuristics





谢谢大家!

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