

CENTRE NATIONAL DE LA RECHERCHE SCIENTIFIQUE





## ABSTRACT

- 1. TLCE A Temporal Logic with Constrained Events a) temporal relationships among input and output (I/O) events b) data dependencies between event parameters
- 2. TLCE-based symbolic test generation algorithm
- 3. Case Study: Conference Protocol
- 4. Case Study: Cache Coherence Protocol

## 1 Introduction

## 1.1 Model-Based Testing

- Automated generation of efficient test cases using system models and specified properties
- Particularly useful for testing of concurrent systems (more difficult to find oracles)

## 1.2 STG - Symbolic Test Generation

- [1, 2, 3] "restricted to the control structure" the data dependencies between event parameters are
- ignored, which would result in less precise test cases • improved through an approximate analysis on reachability/co-reachability [4]
- But in practice, it is still tedious and error-prone to represent test purposes as transition systems

## Example - Bluetooth Service Discovery Protocol (SDP)

[TP] - After a Partial Service Response message with a Continuation State parameter sent to the SUT, a subsequent *Service Request will be received with the same Continuation State parameter.* In this case, all partial response messages should use the same session identifiers as specified in preceding request messages.

#### 1.3 Our Approach [5]

**System Models** *Symbolic Transition Graphs* - extended FSM with state variables and I/O actions

Property Specification Temporal Logic with Constrained Events (TLCE) - formulas as test purposes

**Test Case Generation** *slicing* the model with respect to formulas

#### Main Advantage:

- Can specify **both** synchronization behaviors and input-output data-dependency
- Can release the effort in constructing transition systems for test purposes
- Can support for a wider range of temporal properties to be adopted for automated test generation

#### **1.4 Not Quite Clear**

• PSCL takes a CTL (Computation Tree Logic) [6] like syntax, but the semantic interpretation of the temporal operator X ("next") in PSCL depends on the preceding path quantifier

#### **1.5 Main Contribution**

- TLCE an extension of PSCL with model operators  $\langle \rangle$  and [] [7]
- TLCE-based symbolic test generation algorithm

## 2 TLCE

Path Formula  $\eta$  ::=  $\mathbf{G} arphi$ 



- Syntactic Categories
- Let *Val* be a set of values, ranged over by v
- Let *Var* be a set of variables, ranged over by x, y, z
- *b* is a boolean expression over  $Val \cup Var$
- *a* is a channel name
- The parameters of an output event are *variables*, not expressions
- one can only obtain the output data without prior knowledge of how it was computed by the system under test (black-box testing)
- the output data could be referred to in subsequent data dependency constraints

**Example** [TP] -  $\mathbf{AG}([sdpRsp?(sid_1, cs_1) : cs_1 \neq NULL]\mathbf{A}(tt \mathbf{U}(sdpReq!(sid_2, cs_2) : cs_2 = cs_1)tt))$ 

## **3** TLCE-based Symbolic Test Generation

- sitions
- 3. Customize the resulting model slice as a symbolic test case according to the data dependency constraints specified in  $\varphi$

# TLCE formula $\mathbf{EF}(\langle a?x : x \geq 3 \rangle \mathbf{EF}(\langle ok!p : p == 2 \rangle tt))$ , where $\mathbf{EF}(\varphi) = \mathbf{E}(tt \mathbf{U} \varphi)$ .



## 3.1 Determinization

a) Collecting Observable Transitions



## Hypothesis - the system model does not contain a cycle of internal transitions.

b) Eliminating Conflict Transitions



Herein, even with conflict guards on the same output actions, the target nodes can still be distinguished if the output results are different. Therefore, the conflict condition above is  $b_1 \wedge b_2 \wedge \bar{e}_1 = \bar{e}_2$ .

## 3.2 TLCE-Based Slicing

A model slice consists of *potential* witnesses supporting the given test purpose. The *characteristic vector*  $CV(\varphi)$ in the form of  $(c_1, \dots, c_{|N|})^T$  is defined to compute out recursively the model slice with respect to  $\varphi$ . Let  $CV_i(\varphi)$  be the *i*-th element of  $CV(\varphi)$ , i.e.  $c_i$ . For  $n_i \in N$ ,  $n_i \vdash \varphi$  if  $CV_i(\varphi) = 1$ .

arphi	
$f\!f$	
tt	
$\psi_1 \wedge \psi_2$	
$\psi_1 \lor \psi_2$	
$\langleeta:b anglearphi$	
[eta:b]arphi	
	C
$\varphi$	$V_0$
$\mathbf{A}[\psi_1 \mathbf{U} \psi_2]$	$CV(\psi_2$
$\mathbf{E}[\psi_1 \ \mathbf{U} \ \psi_2]$	$CV(\psi_2$
(0)	(
$\varphi$	$V_0$
$\mathbf{A}[\psi_1 \mathbf{R} \psi_2]$	$CV(\psi_2$
$\mathbf{E}[\psi_1 \mathbf{R} \psi_2]$	$CV(\psi_2$
$\mathbf{A}[\mathbf{G} \ \psi]$	$CV(\psi)$
$\mathbf{E}[\mathbf{G} \ \psi]$	$CV(\psi)$
	•

## 3.3 Customizing Model Slices

- and append a trap edge  $n \xrightarrow{o} trap$ ;
- no  $\alpha_{\beta}$ -derivative, append a trap edge  $n \xrightarrow{\alpha_{\beta}} trap;$
- $\alpha_{\beta}$ -derivatives *m* of *n*, append *m*  $\xrightarrow{verdict!INCONC}$  \$.
- 4. If  $trap \in N_t$ , append  $trap \xrightarrow{verdict!FAIL}$  \$.

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# Symbolic Test Generation Using a Temporal Logic with Constrained **Events**

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Given a system model G(N) and a test purpose  $\varphi$  in TLCE, the workflow of our approach is as follows: 1. Make the system model deterministic by eliminating internal transitions and resolving conflict I/O tran-

2. Slice the resulting model according to the temporal relationship specified in  $\varphi$ 

**Example** The test purpose represented as a transition system in Fig. 2 of [4] can be directly described as a







 $b_2, \theta_2, c! \bar{e}_2 \qquad b_1 \land (\neg b_2 \lor \bar{e}_1 \neq \bar{e}_2), \theta_1, c! \bar{e}_1 \neq b_2 \land (\neg b_1 \lor \bar{e}_1 \neq \bar{e}_2), \theta_2, c! \bar{e}_2 \qquad b_2 \land (\neg b_1 \lor \bar{e}_1 \neq \bar{e}_2), \theta_2, c! \bar{e}_2 = b_1 \land (\neg b_2 \lor \bar{e}_1 \neq \bar{e}_2), \theta_1, c! \bar{e}_1 \neq b_2 \land (\neg b_1 \lor \bar{e}_1 \neq \bar{e}_2), \theta_2, c! \bar{e}_2 = b_1 \land (\neg b_2 \lor \bar{e}_1 \neq \bar{e}_2), \theta_1, c! \bar{e}_1 \neq b_2 \land (\neg b_1 \lor \bar{e}_1 \neq \bar{e}_2), \theta_2, c! \bar{e}_2 = b_1 \land (\neg b_2 \lor \bar{e}_1 \neq \bar{e}_2), \theta_1, c! \bar{e}_1 \neq b_2 \land (\neg b_1 \lor \bar{e}_1 \neq \bar{e}_2), \theta_2, c! \bar{e}_2 = b_1 \land (\neg b_2 \lor \bar{e}_1 \neq \bar{e}_2), \theta_2, c! \bar{e}_2 = b_1 \land (\neg b_2 \lor \bar{e}_1 \neq \bar{e}_2), \theta_2, c! \bar{e}_2 = b_1 \land (\neg b_2 \lor \bar{e}_1 \neq \bar{e}_2), \theta_2, c! \bar{e}_2 = b_1 \land (\neg b_2 \lor \bar{e}_1 \neq \bar{e}_2), \theta_2, c! \bar{e}_2 = b_1 \land (\neg b_2 \lor \bar{e}_1 \neq \bar{e}_2), \theta_2, c! \bar{e}_2 = b_1 \land (\neg b_2 \lor \bar{e}_1 \neq \bar{e}_2), \theta_2, c! \bar{e}_2 = b_1 \land (\neg b_2 \lor \bar{e}_1 \neq \bar{e}_2), \theta_2, c! \bar{e}_2 = b_1 \land (\neg b_2 \lor \bar{e}_1 \neq \bar{e}_2), \theta_2, c! \bar{e}_2 = b_1 \land (\neg b_2 \lor \bar{e}_1 \neq \bar{e}_2), \theta_3 \land (\neg b_1 \lor \bar{e}_1 \neq \bar{e}_2), \theta_4 \land (\neg b_2 \lor \bar{e}_2 \neq \bar{e}_2), \theta_4 \land (\neg b_2 \lor \bar{e}_1 \neq \bar{e}_2), \theta_4 \land (\neg b_2 \lor \bar{e}_1 \neq \bar{e}_2), \theta_4 \land (\neg b_2 \lor \bar{e}_2 \neq \bar{e}_2)$  $\implies \qquad n_1 \qquad \stackrel{\bigvee b_1 \wedge b_2 \land \overline{b_1} = \overline{e}_2, c \mid \overline{e}_1}{n_{1,2}} \qquad n_2$  $b, \theta, \alpha$   $b' \theta_2, \theta_2 \theta', \alpha' \theta_2$   $b', \theta', \alpha'$  $\psi_{\mu} b\theta_1, \theta_1 \theta, \alpha \theta_1$ 

CV(arphi)
$c_i = 0, 1 \le i \le  N $
$c_i = 1, 1 \le i \le  N $
$CV(\psi_1) * CV(\psi_2)$
$CV(\psi_1) + CV(\psi_2)$
$CM(\beta) \times CV(\varphi)$
$CM(\beta) \circ CV(\varphi)$
$V(\varphi) = \mu V. V + g(V)$
g(V)
$CV(\psi_1) * (CM(G) \odot V)$
$CV(\psi_1) * (CM(G) \otimes V)$
$V(\varphi) = \nu V. \ V * g(V)$
g(V)
$CV(\psi_1) + (CM(G) \odot V)$
$CV(\psi_1) + (CM(G) \otimes V)$
$CM(G) \circ V$
$CM(G) \times V$

Let  $\bar{z}_{\beta}$  and  $\bar{v}_{\alpha_{\beta}}$  denote the parameters of the event  $\beta$  and the corresponding action  $\alpha_{\beta}$ , respectively,

1. For each  $n \in N_{\varphi}$  and  $n \vdash \langle \beta : b \rangle tt$ , two outgoing edges,  $(\neg b[\bar{v}_{\alpha_{\beta}}/\bar{z}_{\beta}], verdict!FAIL)$  and  $(b[\bar{v}_{\alpha\beta}/\bar{z}_{\beta}], verdict!PASS)$  are attached to every immediate  $\alpha_{\beta}$ -derivative of *n* in  $N_{\omega}$  with \$ as end nodes;

2. For each  $n \in N_{\omega}$  and  $n \vdash [\beta : b]ff$ , two outgoing edges,  $(\neg b[\bar{v}_{\alpha_{\beta}}/\bar{z}_{\beta}], verdict!PASS)$  and  $(b[\bar{v}_{\alpha_{\beta}}/\bar{z}_{\beta}], verdict!FAIL)$  are attached to every  $\alpha_{\beta}$ -derivative of *n* in  $N_{\varphi}$  with \$ as end nodes; If *n* has

3. if  $n \in N_{\varphi}$  and  $n \vdash [\beta : b]\psi$  (or  $\langle \beta : b \rangle \psi$ ) with  $\varphi \not\equiv tt$  (or *ff*), then for every  $\alpha_{\beta}$ -derivatives *n'* of *n* which satisfies  $\varphi$ , each outgoing edge  $(b_1, \theta, \alpha)$  of n' is substituted with  $(b_1 \wedge b[\bar{v}_{\alpha_\beta}/\bar{z}_\beta], (\bar{z}_\beta := \bar{v}_{\alpha_\beta})\theta, \alpha)$ ; while one outgoing edge  $(\neg b[\bar{v}_{\alpha\beta}/\bar{z}_{\beta}], verdict!INCONC)$  is attached to n' with \$ as the end node; for any non

## 4 Case Studies

We have implemented the TLCE-based symbolic test generation algorithm in Object Caml. The TorX tool environment [8] was used as the execution engine for test campaigns, which proceeded as follows:

- 1. Generate symbolic test cases with regards to given test purposes
- 2. Derive parameterized test sequences, associated with specified data dependency constraints
- 3. Instantiate the input and output parameters, using a constraint solver Bonus [9], to produce executable test cases
- 4. Convert executable test cases as test specifications for TorX
- 5. Perform random testing in TorX within the fixed number of steps

## 4.1 Conference Protocol [10]

The protocol provides a multicast chatbox service to its user. Each user can initiate a conference, which users can join and leave at any time. Each user in a conference can exchange messages with all other users in the conference.

**System Model** 3 conference users, 22 nodes and 189 reachable transitions

**Property Specifications** 14 test purposes

Test Case Generation 287 test cases, full state and transition coverage

**Mutants** 15 erroneous mutants of the protocol, distributed within the TorX example package

Test Result TorX is configured to run automatically no more than 35 steps.

No	D	Б	т	ED	c	TorX	
10.	Г	Г	1	гD	5	Result	S
14	105	182	0	63.00%	25	FAIL	13
16	69	218	0	75.00%	23	FAIL	27
17	0	211	76	73.00%	2	FAIL	2
18	91	196	0	68.00%	25	FAIL	15
19	210	77	0	26.00%	20	FAIL	19
20	69	218	0	75.00%	23	FAIL	27
22	28	259	0	90.00%	10	FAIL	27
23	219	68	0	23.00%	19	FAIL	17
24	203	84	0	29.00%	20	FAIL	14
27	22	265	0	92.00%	7	FAIL	23
28	221	66	0	22.00%	21	FAIL	18
31	209	78	0	27.00%	20	FAIL	15
32	205	82	0	28.00%	20	PASS	-
33	208	79	0	27.00%	20	FAIL	24
60	22	265	0	92.00%	7	FAIL	13
MS	100%				93%		

- Better Mutation Score (MS) (100% vs. 93%)
- Mutant 32 can not be detected by the TorX test specification within 35 steps
- FD fault detection ratio, i.e. the ratio between the number of failed test cases and the total number of test cases [11]
- No effort is required to design test cases for particular mutants

## 4.2 Cache Coherence Protocol [12]

The protocol aims to maintain the cache coherence among multi-processors with shared memory.

**System Model** 3 processes, based on the formal description of the protocol presented in [13]

**Property Specification** 6 test purposes

**Test Case Generation** 730 test cases, full state and transition coverage

**Mutants** 14 erroneous mutants

**Test Result** The column *TorX* shows the test results with 300 random test cases generated by TorX.

No	FD(%)	S	TorX	
INO.			FD(%)	S
1	64.79	11.39	99.50	9.42
2	64.79	11.39	97.00	10.10
3	13.42	8.41	-	-
4	22.19	5.08	-	-
5	0.14	2.00	-	-
6	37.53	11.96	40.50	19.98
7	0.27	4.50	14.00	19.54
8	6.03	12.55	-	-
9	10.82	14.19	39.50	18.63
10	1.23	7.44	19.50	16.95
11	20.00	29.30	-	-
12	0.68	19.10	30.00	21.53
13	38.36	4.00	-	-
14	0.96	14.92	29.50	19.97

- Better Mutation Score (100% vs. 57.14%)
- Most mutants can be detected by the symbolic test cases within a fairly small number of steps.
- For those mutants that can be detected by both methods, the FDs of the symbolic test cases are less than those of the random test cases.
- conforms to the observation stated in [4] on accurate test cases
- A random test case, which is not correspondent to any test purpose, would drive the system under test to exhibit non-conformance more possibly
- A symbolic test case, which reflects accurately the guiding test purpose, would show less capability of detecting errors that are not related to that test purpose



## **5** Conclusions

- TLCE a better way to express test purposes involving data dependencies between event parameters
- Case studies have shown the effectiveness and efficiency of our approach

## **Future Work**

• Integration with the symbolic testing framework [4] – Symbolic test execution engine

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## A Constraint Oriented Slicing Algorithm

During the iterative computation of  $CV(\varphi)$ , the program model is sliced simultaneously. The following illustrates the slicing algorithm based on the fixed point definitions of TLCE(PSCL) constraints.

function lfp-slicing(
$$V_0, g, N, E$$
) =  
 $V = V_0; DV = g(V); V' = V + DV;$   
 $N = \{n_k \mid DV(k) = 1\} \cup N;$   
 $E = \{n_k \xrightarrow{b,\theta,\alpha} n_l \mid DV(k) = 1, V(l) = 1\} \cup E;$   
while  $V' \neq V$  do  
 $DV = g(V); V' = V + DV;$   
 $N = \{n_k \mid DV(k) = 1\} \cup N;$   
 $E = \{n_k \xrightarrow{b,\theta,\alpha} n_l \mid DV(k) = 1, V(l) = 1\} \cup E;$   
end while;  
return  $(V, N, E)$   
end function  
function gfp-slicing( $V_0, g, N, E$ ) =  
 $V = V_0; DV = g(V); V' = V * DV;$   
 $N = \{n_k \mid DV(k) = 1\} \cup N;$   
 $E = \{n_k \xrightarrow{b,\theta,\alpha} n_l \mid DV(k) = 1, V(l) = 1\} \cup E;$   
while  $V' \neq V$  do  
 $DV = g(V); V' = V * DV;$   
 $N = \{n_k \mid DV(k) = 1\} \cup N;$   
 $E = \{n_k \xrightarrow{b,\theta,\alpha} n_l \mid DV(k) = 1, V(l) = 1\} \cup E;$   
end while;  
return  $(V, N, E)$   
end function